

CS200 Algorithms and Data Structures : Quiz 6 and 7

Problem 1 ~ 10: 5 pts each

- 1) In an unsorted array-based implementation of a table, a new item is inserted at location _____.
a) items[# of items] b) items[# of items - 1]
c) items[# of items + 1] d) items[# of items + 2]

- 2) A priority queue orders its items by their _____.
a) Position b) value c) priority value d) size

- 3) A heap is a _____.
a) general tree b) binary search tree c) full binary tree d) complete binary tree

- 4) In an array-based implementation of a heap, the heapDelete (delete and adjust) operation is _____.
a) $O(1)$ b) $O(n)$ c) $O(n^2)$ d) $O(\log n)$

- 5) The heapsort is _____ in the average case.
a) $O(1)$ b) $O(n)$ c) $O(\log n)$ d) $O(n \log n)$

- 6) The mergesort is more efficient than the heapsort in the worst case.

(True/False)

- 7) A sorted implementation of a table can insert a new item into any convenient location.

(True/False)

- 8) The search key of an item must not change for as long as the item is stored in a table.

(True/False)

- 9) What are the differences between a heap and a binary search tree?

- 10) What is a collision in hashing?

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11) A subset of a graph's vertices and edges is known as a _____.
a) bar graph b) line graph c) subgraph d) circuit

12) A graph is _____ if each pair of distinct vertices has a path between them.
a) Complete b) disconnected c) connected d) full

13) A complete graph has a(n) _____ between each pair of distinct vertices.
a) Edge b) path c) cycle d) circuit

14) An iterative DFS traversal algorithm uses a(n) _____.
a) List b) array c) queue d) stack

15) An iterative BFS traversal algorithm uses a(n) _____.
a) List b) array c) queue d) stack

16) All paths begin and end at the same vertex. (True/False)

17) All complete graphs are connected. (True/False)

18) The adjacency matrix for an undirected graph is symmetrical. (True/False)

19) In a digraph, there can be only one edge between a pair of vertices. (True/False)

20) What are the two most common implementations of a graph?