



Dynamic Hashing

Database System Concepts, 6th Ed.

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Deficiencies of Static Hashing

- In static hashing, function h maps search-key values to a fixed set of B of bucket addresses. Databases grow or shrink with time.
 - If initial number of buckets is too small, and file grows, performance will degrade due to too much overflows.
 - If space is allocated for anticipated growth, a significant amount of space will be wasted initially (and buckets will be underfull).
 - If database shrinks, again space will be wasted.
- One solution: periodic re-organization of the file with a new hash function
 - Expensive, disrupts normal operations
- Better solution: allow the number of buckets to be modified dynamically.

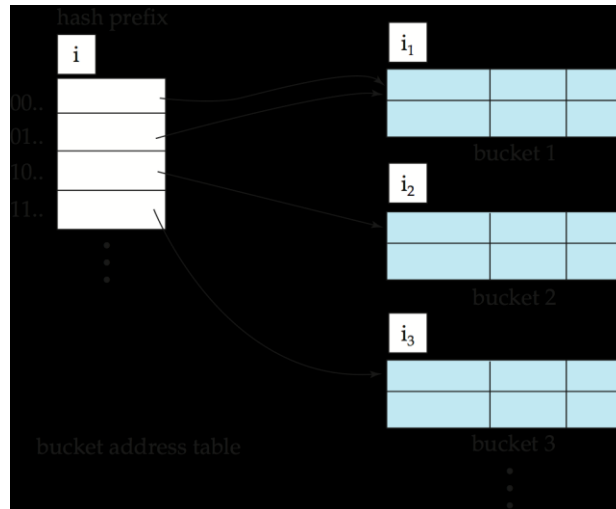


Dynamic Hashing

- Good for database that grows and shrinks in size
- Allows the hash function to be modified dynamically
- **Extendable hashing** – one form of dynamic hashing
 - Hash function generates values over a large range — typically b -bit integers, with $b = 32$.
 - At any time use only a prefix of the hash function to index into a table of bucket addresses.
 - Let the length of the prefix be i bits, $0 \leq i \leq 32$.
 - ▶ Bucket address table size = 2^i . Initially $i = 0$
 - ▶ Value of i grows as the size of the database grows.
 - Multiple entries in the bucket address table may point to a bucket (why?)
 - Thus, actual number of buckets is $< 2^i$
 - ▶ The number of buckets also changes dynamically due to coalescing and splitting of buckets.



General Extendable Hash Structure



In this structure, $i_2 = i_3 = i$, whereas $i_1 = i - 1$ (see next slide for details)



Use of Extendable Hash Structure

- Each bucket j stores a depth i
 - All the entries that point to the same bucket have the same first i bits.
- To locate the bucket containing search-key K_j :
 1. Compute $h(K_j) = X$
 2. Use the first i high order bits of X as a displacement into bucket address table, and follow the pointer to appropriate bucket
- To insert a record with search-key value K_j
 - follow same procedure as look-up and locate the bucket, say j .
 - If there is room in the bucket j insert record in the bucket.
 - Else the bucket must be split and insertion re-attempted (next slide.)
 - ▶ Overflow buckets used instead in some cases (will see shortly)



Insertion in Extendable Hash Structure (Cont)

To split a bucket j when inserting record with search-key value K_j :

- Compare local depth to global depth
- If local depth == global depth,
 - Double directory size
 - Increase global depth by 1 bit
- Split bucket using 1 extra bit
- Adjust directory entry appropriately



Hash key is department code

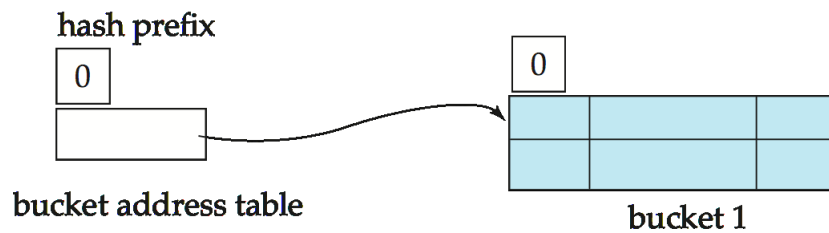
dept_name

Biology	0010
Comp. Sci.	1111
Elec. Eng.	0100
Finance	1010
History	1100
Music	0011
Physics	1001



Example (Cont.)

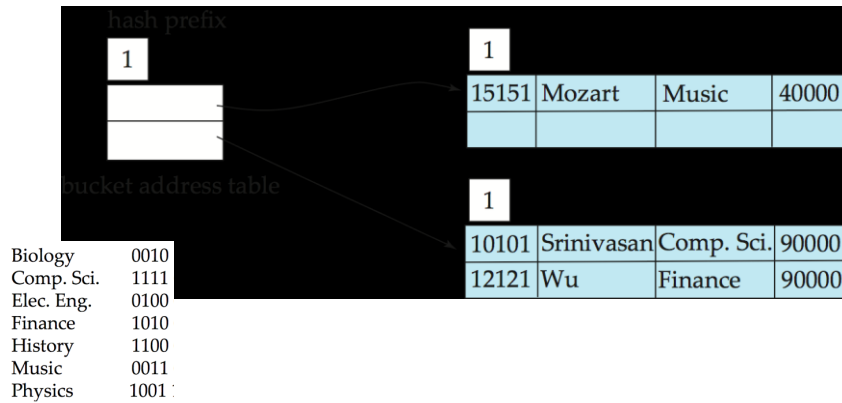
- Initial Hash structure; bucket size = 2





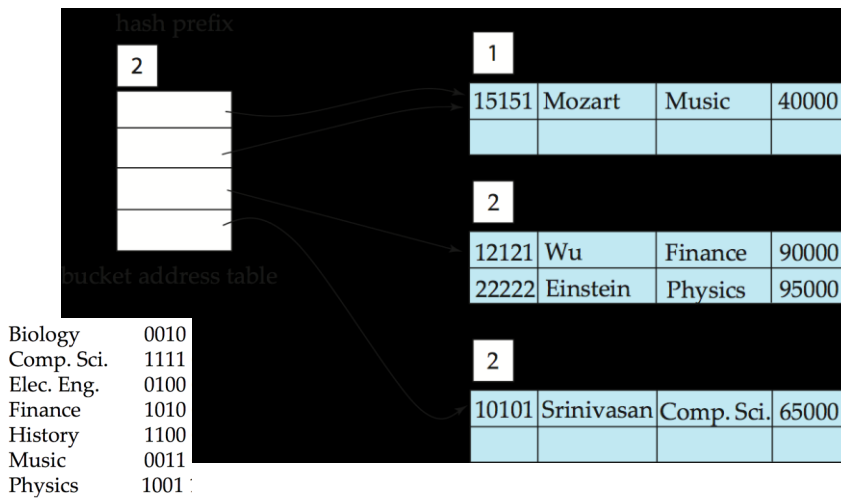
Example (Cont.)

- Hash structure after insertion of “Mozart”, “Srinivasan”, and “Wu” records



Example (Cont.)

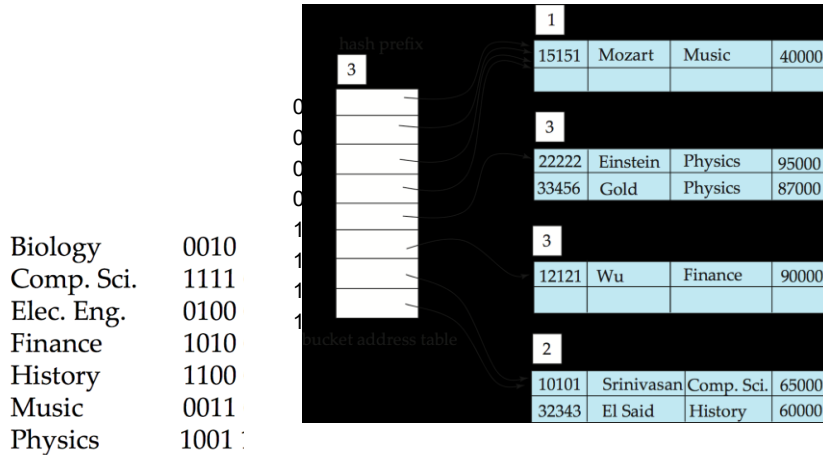
- Hash structure after insertion of Einstein record





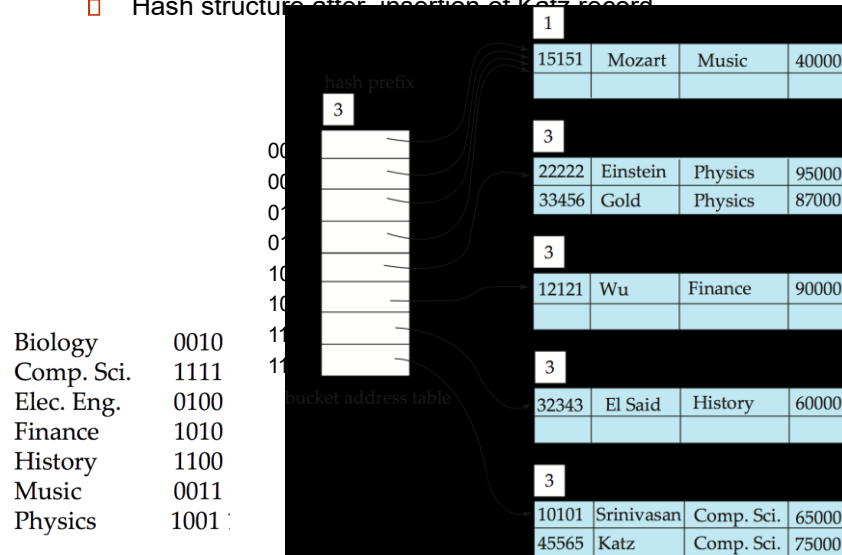
Example (Cont.)

□ Hash structure after insertion of Gold and El Said records



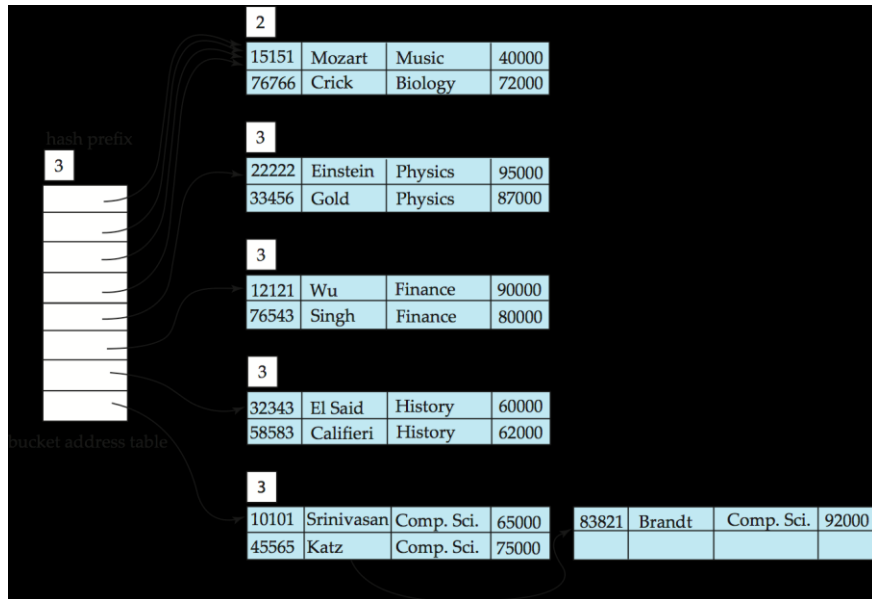
Example (Cont.)

□ Hash structure after insertion of Katz record





Example (Cont.)



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Extendable Hashing vs. Other Schemes

- Benefits of extendable hashing:
 - Hash performance does not degrade with growth of file
 - Minimal space overhead
- Disadvantages of extendable hashing
 - Extra level of indirection to find desired record
 - Bucket address table may itself become very big (larger than memory)
 - Changing size of bucket address table is an expensive operation

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