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package thread_ex;
public class Thread_ex {

    boolean done = false;

    public Thread_ex(int NumT1, int NumT2) {

        /*
         * Constructor for the main class, its function is to spawn the
         * T1 and T2 threads
         */
        for (int i = 0; i < NumT1; i++) {
            new T1().start();
        }
        for (int i = 0; i < NumT2; i++) {
            new T2().start();
        }

    }

    public class T1 extends Thread {
        /*
         * T1 sleeps until done
         */
        public void run() {
            System.out.println ("T1 thread started");
            while (!done) {
                try {

                    Thread.sleep(1000);
                } catch (InterruptedException ex) {
                    System.out.println("Interrupt in T1");
                }

            }
            System.out.println ("T1 thread finished");
        }
    }

    public class T2 extends Thread {
        /*
         * T1 sleeps until done
         */
        public void run() {
            System.out.println ("T2 thread started");
            while (!done) {
                try {

                    Thread.sleep(1000);
                } catch (InterruptedException ex) {
                    System.out.println("Interrupt in T2");
                }

            }
            System.out.println ("T2 thread finished");
        }
    }

    public static void main(String[] args) {
        Thread_ex tex = new Thread_ex(2,2);
        /*
         * Sleep for 5 seconds and kill
         */
        try {
            Thread.sleep(5000);
        } catch (InterruptedException e) {

        }
        tex.done = true;
        System.out.println("main finished");
    }
}

```

```

T1 thread started
T1 thread started
T2 thread started
T2 thread started
main finished
T2 thread finished
T2 thread finished
T1 thread finished
T1 thread finished

```

1) What are the advantages of the one-to-one user/kernel thread model? Disadvantages? How about the many-to-many model?

2) What are the 4 options available for handling signals delivered to a multi-threaded process? When might you use them?

3) What are the two types of cancellation for threads? When might you use them?

4) What is the issue with `fork()` and `exec()`? How can it be handled?