Schedule Code Generator for SubSystem

Given an affine system with subsystems/useEquations, this page shows how to specify the targetmapping for the system and generate the code.

Example program with subsystem

The following code is the alpha program for matrix matrix multiplication with dot-product subsystem.

```
affine matrix_product_SubSyst {N,K,M | N>0 && K>0 && M > 0}    // Product
between a N*K matrix and a K*M matrix
input
    float A {i,k | 0<=i<N && 0<=k<K};
    float B {k,j | 0<=k<K && 0<=j<M};
output
    float C {i,j | 0<=i<N && 0<=j<M};
let
    use {iP,jP|0<=iP<N && 0<=jP<M} dot_product[K]
((pi,pj,k->pi,k)@A,(pi,pj,k->k,pj)@B) returns (C);
.

affine dot_product {N| N>0}  // Product between 2 vector of size N
input
    float vect1 {i | 0<=i<N };
    float vect2 {i | 0<=i<N };
output
    float Res;
local
    float temp {i | 0<=i<N};
let
    temp[i] = case
        {i|i==0}   : vect1[0] * vect2[0];
        {i |0<i<N} : temp[i-1] + vect1[i]*vect2[i];
    esac;
    Res[] = temp[N-1];
.
```

The program contains two systems. The dot_product system takes two vectors as inputs and computes the doc product of these two vectors. The matrix_product_SubSyst computes matrix C=A*B, the (ip,jp)th element for the answer matrix C is computed by calling the dot product subsystem, and the (ip)th row of A, and (jp)th column of B is passed as input to the subsystem call.

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