CS370 Operating Systems

Colorado State University Yashwant K Malaiya Spring 2022 Lecture 7



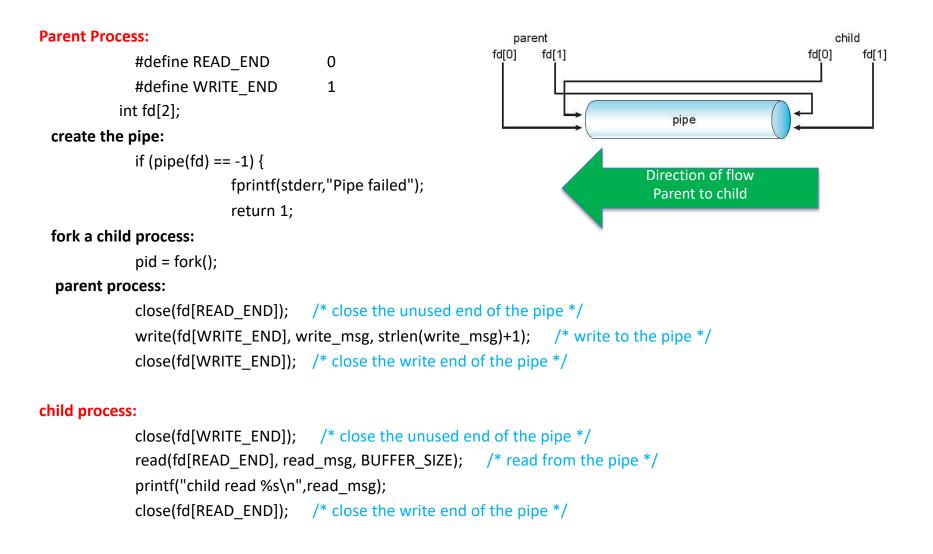
Slides based on

- Text by Silberschatz, Galvin, Gagne
- Various sources

Today

- Threads
- Amdahl's law
- Kernel support for threads
- Pthreads
- Java Threads
- Implicit threading

UNIX pipe example





CS370 Operating Systems

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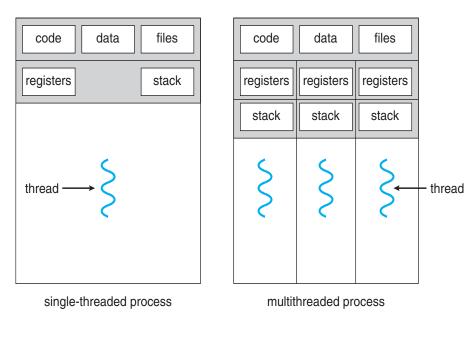
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Chapter 4: Threads

Objectives:

- Thread—basis of multithreaded systems
- APIs for the Pthreads and Java thread libraries
- implicit threading, multithreaded programming
- OS support for threads





Multicore Programming

- Multicore or multiprocessor systems putting pressure on programmers, challenges include:
 - Dividing activities
 - Balance
 - Data splitting
 - Data dependency
 - Testing and debugging
- Parallelism implies a system can perform more than one task simultaneously
 - Extra hardware needed for parallel execution
- Concurrency supports more than one task making progress
 - Single processor / core: scheduler providing concurrency

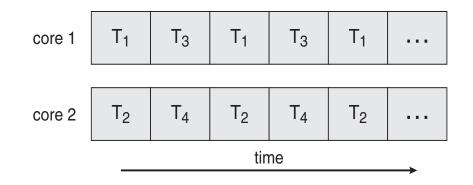


Concurrency vs. Parallelism

Concurrent execution on single-core system:



Parallelism on a multi-core system:



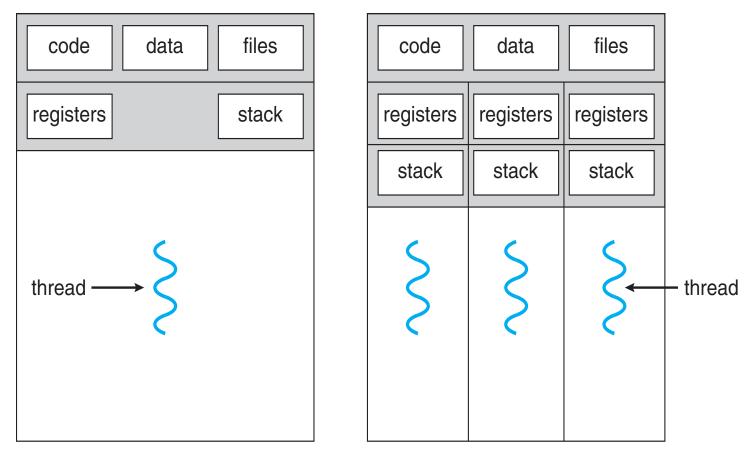
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Multicore Programming (Cont.)

- Types of parallelism
 - Data parallelism distributes subsets of the same data across multiple cores, same operation on each
 - Task parallelism distributing threads across cores, each thread performing unique operation
- As # of threads grows, so does architectural support for threading
 - CPUs have cores as well as *hardware threads*
 - e.g. hyper-threading
 - Oracle SPARC T4 with 8 cores, and 8 hardware threads per core (total 64 threads)
 - AMD Ryzen 7 with 4 cores and 8 threads



Single and Multithreaded Processes



multithreaded process

single-threaded process

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Process vs Thread

- All threads in a process have same address space (text, data, open files, signals etc.), same global variables
- Each thread has its own
 - Thread ID
 - Program counter
 - Registers
 - Stack: execution trail, local variables
 - State (running, ready, blocked, terminated)
- Thread is also a schedulable entity



Amdahl's Law

Identifies performance gains from adding additional cores to an application that has both serial and parallel components.

- *S* is serial portion (as a fraction) that cannot be broken into parallel operations.
- Some things can possibly be done in parallel.
- *N* processing cores

$$speedup \le \frac{1}{S + \frac{(1-S)}{N}}$$

- Example: if application is 75% parallel / 25% serial, moving from 1 to 2 cores results in speedup of 1/(0.25+ 0.75/2) = 1.6 times
- As *N* approaches infinity, speedup approaches 1 / *S*

Serial portion of an application has disproportionate effect on performance gained by adding additional cores

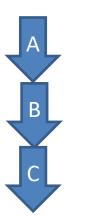


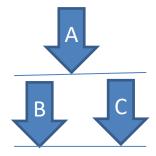
Amdahls law: ordinary life example

• Amdahls law: ordinary life example.

Which of the two option is faster?

- Person A cooks, person B eats and then Person C eats.
- Person A cooks, then both person B and person C eat at the same time.







User Threads and Kernel Threads

- User threads management done by user-level threads library
- Three main thread libraries:
 - POSIX Pthreads
 - Windows threads
 - Java threads
- Kernel threads Supported by the Kernel
 - Examples virtually all general-purpose operating systems, including:
 - Windows
 - Linux
 - Mac OS X



Multithreading Models

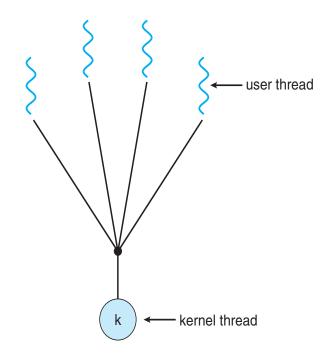
How do kernel threads support user process threads?

- Many-to-One: Many user-level threads mapped to single kernel thread (thread library in user space older model)
- One-to-One: (now common)
- Many-to-Many: Allows many user level threads to be mapped to smaller or equal number of kernel threads (older systems)



Many-to-One

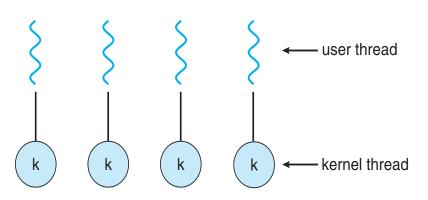
- Many user-level threads mapped to single kernel thread (thread library in user space older model)
- One thread blocking causes all to block
- Multiple threads may not run in parallel on muticore system because only one may be in kernel at a time
- Few systems currently use this model
- Examples:
 - Solaris Green Threads for Java 1996
 - GNU Portable Threads 2006





One-to-One

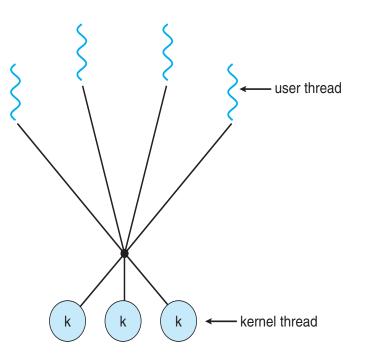
- Each user-level thread maps to kernel thread
- Creating a user-level thread creates a kernel thread
- More concurrency than many-to-one
- Number of threads per process
 sometimes restricted due to overhead
- Examples
 - Windows
 - Linux
 - Solaris 9 and later





Many-to-Many Model

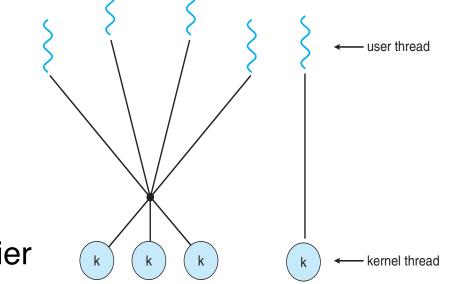
- Allows many user level threads to be mapped to smaller or equal number of kernel threads
- Allows the operating system to create a sufficient number of kernel threads
- Solaris prior to version 9
- Windows with the *ThreadFiber* package NT/2000





Two-level Model

- Similar to M:M, except that it allows a user thread to be **bound** to a kernel thread
- Examples
 - IRIX -2006
 - HP-UX
 - Tru64 UNIX
 - Solaris 8 and earlier





Thread Libraries

- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS



POSIX Pthreads

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization 1991
- Specification, not implementation
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Solaris, Linux, Mac OS X)



Some Pthread management functions

POSIX function Description pthread_cancel Terminate a thread pthread create Create a thread Set thread to release resources pthread_detach pthread_exit Exit a thread without exiting process pthread kill Send a signal to a thread Wait for a thread pthread join pthread self Find out own thread ID

Return 0 if successful



POSIX: Thread creation pthread_create()

- Automatically makes the thread runnable without a start operation
- Takes 3 parameters:
 - Points to ID of newly created thread
 - Attributes for the thread
 - Stack size, scheduling information, etc.
 - Name of function that the thread calls when it begins execution with argument
- /* create the thread */

```
pthread_create(&tid, &attr, runner, argv[1]);
```



POSIX: Detaching and Joining

- pthread_detach()
 - Sets internal options to specify that storage for thread can be reclaimed when it exits
 - 1 parameter: Thread ID of the thread to detach
 - Undetached threads don't release resources until
 - Another thread calls pthread_join for them
 - Or the whole process exits
- pthread_join
 - Takes ID of the thread to wait for
 - Suspends calling thread till target terminates
 - Similar to waitpid at the process level pthread_join(tid, NULL);



- If a process calls exit, **all** threads terminate
- Call to pthread_exit causes only the calling thread to terminate

pthread_exit(0)

- Threads can force other threads to return through a *cancellation* mechanism
 - pthread_cancel (): takes thread ID of target
 - Actual cancellation depends on type and state of thread



Pthreads Example (next 2 slides)

- This process will have two threads
 - Initial/main thread to execute the main () function. It crates a new thread and waits for it to finish.
 - A new thread that runs function runner ()
 - It will get a parameter, an integer, and will compute the sum of all integers from 1 to that number.
 - New thread leaves the result in a global variable **sum**.
 - The main thread prints the result.



Pthreads Example Pt 1

#include <pthread.h>
#include <stdio.h>

```
int sum; /* this global data is shared by the thread(s) */
```

```
void *runner(void *param); /* the thread */
```

```
int main(int argc, char *argv[])
{
    pthread_t tid; /* the thread identifier */
    pthread_attr_t attr; /* set of attributes for the thread */
```

```
if (argc != 2) {
    fprintf(stderr,"usage: a.out <integer value>\n");
    /*exit(1);*/
    return -1;
}
```

```
 \text{if } (\operatorname{atoi}(\operatorname{argv}[1]) < 0) \; \{ \;
```

fprintf(stderr,"Argument %d must be non-negative\n",atoi(argv[1]));
/*exit(1);*/
return -1;

thread runner will perform summation of integers 1,2, ..n



}

Pthreads Example Pt 2

```
/* get the default attributes */
pthread_attr_init(&attr);
/* create the thread */
pthread_create(&tid, &attr, runner, argv[1]); <- Second thread begins in runner () function
/* now wait for the thread to exit */
pthread_join(tid, NULL);
```

```
printf("sum = %d\n", sum);
}
/* The thread will begin control in this function */
void *runner(void *param)
int i, upper = atoi(param);
sum = 0;
           if (upper > 0) {
                       for (i = 1; i <= upper; i++)
                                  sum += i;
           pthread exit(0);
}
```

Compile using gcc thrd.c –lpthread

Execution: %./thrd 4 sum = 10



Pthreads Code for Multiple Threads

```
{
    /* do some work ... */
pthread_exit(0);
}
```



Java Threads

- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:
 - Extending Thread class
 - Override its run() method

Runnable interface is defined by

More commonly, implementing the Runnable interface

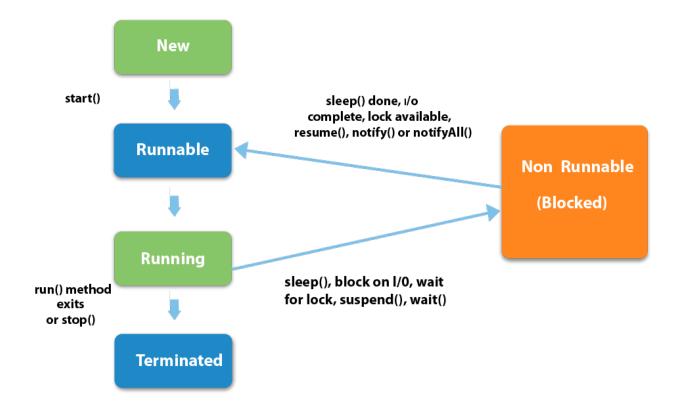
public interface Runnable

public abstract void run();

- 1. Has 1 method run()
- 2. Create new Thread class by passing a l object to its constructor
- 3. start() method creates a new thread by calling the run() method.
- new features available in java.util.concurrent package



Java Thread States



https://www.javatpoint.com/life-cycle-of-a-thread



Ex: Using Java Threads (1/3)

Java version of a multithreaded program that computes summation of a non-negative integer.

This program creates a separate thread by implementing the Runnable interface.

```
class Sum
{
                                                                                Program Overall Structure
              private int sum;
                                                               class sum
                                                               class summation implements runnable
              public int get() {
                                                               { ...
                            return sum:
                                                                  public void run() { .. }
              }
                                                               Public class Driver
              public void set(int sum) {
                                                                { .....
                                                                  public static void main(String[] args) {
                            this.sum = sum;
              }
                                                                   Thread worker = new Thread(new summation( ...
}
                                                                   worker.start();
```

try {

worker.join();

```
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```

Ex: Using Java Threads (2/3)

class Summation implements Runnable

```
private int upper;
private Sum sumValue;
```

//constructor

{

}

```
public Summation(int upper, Sum sumValue) {
```

```
if (upper < 0)
```

throw new IllegalArgumentException();

this.upper = upper; this.sumValue = sumValue;

}

}

//this method runs as a separate thread

```
public void run() {
    int sum = 0;
```

```
for (int i = 0; i <= upper; i++)
sum += i;
```

```
sumValue.set(sum);
```



Ex: Using Java Threads (3/3)

```
public class Driver
          public static void main(String[] args) {
                     if (args.length != 1) {
                                 System.err.println("Usage Driver <integer>");
                                 System.exit(0);
                      }
                     Sum sumObject = new Sum();
                     int upper = Integer.parseInt(args[0]);
                      Thread worker = new Thread(new Summation(upper, sumObject));
                     worker.start( );
                                                            A call to
                     try {
                                worker.join();
                                                             run()
                      } catch (InterruptedException ie) { }
                     System.out.println("The sum of " + upper + " is " + sumObject.get());
          }
```



Implicit Threading

- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- Creation and management of threads done by compilers and run-time libraries rather than programmers
- Three methods explored
 - Thread Pools
 - OpenMP
 - Grand Central Dispatch
- Other methods include Microsoft Threading Building Blocks (TBB), java.util.concurrent package



Implicit Threading1: Thread Pools

- Create a number of threads in a pool where they await work
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool
 - Separating task to be performed from mechanics of creating task allows different strategies for running task
 - i.e.Tasks could be scheduled to run periodically
- Posix thread pools
- Windows API supports thread pools.



Implicit Threading2: OpenMP

- Set of compiler directives and an API for C, C++, FORTRAN
- Provides support for parallel programming in shared-memory environments
- Identifies parallel regions blocks of code that can run in parallel

```
#pragma omp parallel
```

```
Create as many threads as there are cores
```

```
#pragma omp parallel for
  for(i=0;i<N;i++) {
    c[i] = a[i] + b[i];
}
```

Run for loop in parallel

```
Compile using
gcc -fopenmp openmp.c
```

```
#include <omp.h>
#include <stdio.h>
int main(int argc, char *argv[])
{
   /* sequential code */
```

#pragma omp parallel
{
 printf("I am a parallel region.");
}

```
/* sequential code */
```

```
return 0;
```

Self exercise 3, 4 available now.



Implicit Threading3:Grand Central Dispatch

- Apple technology for Mac OS X and iOS operating systems
- Extensions to C, C++ languages, API, and run-time library
- Allows identification of parallel sections
- Manages most of the details of threading
- Block is in "^{ }"
 - ^{ printf("I am a block"); }
- Blocks placed in dispatch queue
 - Assigned to available thread in thread pool when removed from queue



Threading Issues

- Semantics of fork() and exec() system calls
- Signal handling
 - Synchronous and asynchronous
- Thread cancellation of target thread
 - Asynchronous or deferred
- Thread-local storage





Semantics of fork() and exec()

- Does fork() duplicate only the calling thread or all threads?
 - Some UNIXes have two versions of fork
 - 1. when exec() will replace the entire process, dup just that thread
 - 2. duplicate all threads
- exec() usually works as normal replace the running process including all threads



Signal Handling

- **Signals** are used in UNIX systems to notify a process that a particular event has occurred.
- A signal handler is used to process signals
 - 1. Signal is generated by particular event
 - 2. Signal is delivered to a process
 - 3. Signal is handled by one of two signal handlers:
 - 1. default
 - 2. user-defined
- Every signal has **default handler** that kernel runs when handling signal
 - User-defined signal handler can override default
 - For single-threaded, signal delivered to process



Signal Handling (Cont.)

- Where should a signal be delivered for multi-threaded process?
 - Deliver the signal to the thread to which the signal applies?
 - Deliver the signal to every thread in the process?
 - Deliver the signal to certain threads in the process?
 - Assign a specific thread to receive all signals for the process? common



Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is target thread
- Two general approaches:
 - Asynchronous cancellation terminates the target thread immediately
 pthread_setcanceltype (PTHREAD_CANCEL_ASYNCHRONOUS, NULL);
 - Deferred cancellation allows the target thread to periodically check if it should be cancelled
- Pthread code to create and cancel a thread:

```
pthread_t tid;
/* create the thread */
pthread_create(&tid, 0, worker, NULL);
. . .
/* cancel the thread */
pthread_cancel(tid);
```



Thread Cancellation (Cont.)

Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Туре
Off	Disabled	-
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

- A thread's cancelation type (mode) and state can be set.
- If thread has cancellation disabled, cancellation remains pending until thread enables it
 - Default type is deferred
 - Cancellation only occurs when thread reaches cancellation point
 - I.e. pthread_testcancel()
 - Then cleanup handler is invoked
- On Linux systems, thread cancellation is handled through signals



Thread-Local Storage

Thread-local storage (TLS) allows each thread to have its own copy of data

- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
 - Ex: Each transaction has a thread and a transaction identifier is needed.
- Different from local variables
 - Local variables visible only during single function invocation
 - TLS visible across function invocations
- Similar to static data
 - TLS is unique to each thread



Is complexity always good?

- Is something that is
 - More advanced
 - More complex
 - Generally better?

