

# CS 370: OPERATING SYSTEMS

## [CPU SCHEDULING]

Computer Science  
Colorado State University

Instructor: Louis-Noel Pouchet  
Spring 2024

\*\* Lecture slides created by: SHRIDEEP PALICKARA

# Topics covered in this lecture

- Scheduling Algorithms
  - ▣ Priority Scheduling
  - ▣ Lottery scheduling
  - ▣ Round robin scheduling
- Scheduling Examples
  - ▣ Windows, Linux

# Prediction of CPU bursts:

## Make estimates based on past behavior

- $t_n$  : Length of the  $n^{\text{th}}$  CPU burst
- $\tau_n$  : Estimate for the  $n^{\text{th}}$  CPU burst
- $\alpha$  : Controls weight of recent and past history
- $\tau_{n+1} = \alpha t_n + (1-\alpha) \tau_n$
- Burst is predicted as an exponential average of the measured lengths of previous CPU bursts

# $\alpha$ controls the relative weight of recent and past history

- $\tau_{n+1} = \alpha t_n + (1-\alpha) \tau_n$
- Value of  $t_n$  contains our most recent information, while  $\tau_n$  stores the past history
- $\tau_{n+1} = \alpha t_n + (1-\alpha) \alpha t_{n-1} + \dots + (1-\alpha)^j \alpha t_{n-j} + \dots + (1-\alpha)^{n+1} \alpha \tau_0$
- $\alpha$  is less than 1,  $(1-\alpha)$  is also less than one
  - ▣ **Each successive term has less weight than its predecessor**

# The choice of $\alpha$ in our predictive equation

- $\tau_{n+1} = \alpha t_n + (1-\alpha) \tau_n$
- If  $\alpha=0$ ,  $\tau_{n+1} = \tau_n$ 
  - ▣ Current conditions are transient
- If  $\alpha=1$ ,  $\tau_{n+1} = t_n$ 
  - ▣ Only most recent bursts matter
  - ▣ History is assumed to be old and irrelevant

# The choice of $\alpha$ in our predictive equation

- If  $\alpha = 1/2$ 
  - ▣ Recent history and past history are **equally weighted**
- With  $\alpha = 1/2$ ; successive estimates of  $\tau$   
 $t_0/2$      $t_0/4 + t_1/2$      $t_0/8 + t_1/4 + t_2/2$      $t_0/16 + t_1/8 + t_2/4 + t_3/2$ 
  - ▣ By the 3<sup>rd</sup> estimate, weight of  $t_0$  has dropped to  $1/8$ .

# PRIORITY SCHEDULING

# Priority Scheduling

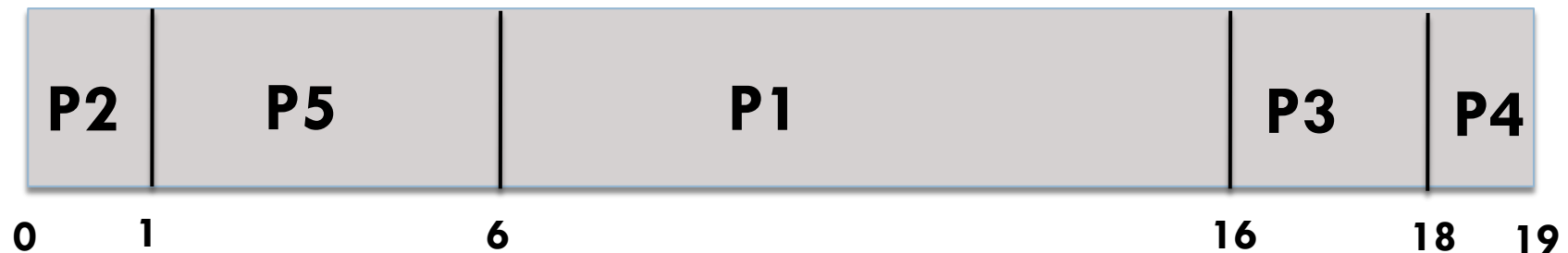
- **Priority** associated with each process
- CPU allocated to process with **highest** priority
- Can be preemptive or nonpreemptive
  - ▣ If preemptive: Preempt CPU from a lower priority process when a higher one is ready



# Depiction of priority scheduling in action

Process	Burst Time	Priority
P1	10	3
P2	1	1
P3	2	4
P4	1	5
P5	5	2

Here: Lower number means higher priority



$$\text{Wait time} = (6 + 0 + 16 + 18 + 1) / 5 = 8.2$$

# How priorities are set

- Internally defined priorities based on:
  - ▣ **Measured** quantities
  - ▣ Time limits, memory requirements, # of open files, ratio (averages) of I/O to CPU burst
- External priorities
  - ▣ Criteria outside the purview of the OS
  - ▣ Importance of process, \$ paid for usage, politics, etc.

# Issue with priority scheduling

- Can leave lower priority processes waiting indefinitely
- Perhaps apocryphal tale:
  - ▣ MIT's IBM 7094 shutdown (1973) found processes from 1967!

# Coping with issues in priority scheduling:

## Aging

- **Gradually increase priority** of processes that wait for a long time
- Example:
  - ▣ Process with priority of 127 and increments every 15 minutes
  - ▣ Process priority becomes 0 in no more than 32 hours

# Can SJF be thought as a priority algorithm?

- Priority is **inverse** of CPU burst
- The larger the burst, the lower the priority

# ROUND ROBIN SCHEDULING

# Round-Robin Scheduling

- Similar to FCFS scheduling
  - ▣ **Preemption** to enable switch between processes
- Ready queue is implemented as **FIFO**
  - ▣ Process Entry: PCB at *tail* of queue
  - ▣ Process chosen: From *head* of the queue
- CPU scheduler goes around ready queue
  - ▣ Allocates CPU to each process *one after the other*
    - CPU-bound up to a maximum of 1 **quantum**

# Round Robin: Choosing the quantum

- Context switch is **time consuming**
  - ▣ Saving and loading registers and memory maps
  - ▣ Updating tables
  - ▣ Flushing and reloading memory cache
- What if quantum is 4 ms and context switch overhead is 1 ms?
  - ▣ 20% of CPU time thrown away in administrative overhead



# Round Robin: Improving efficiency by increasing quantum

- Let's say quantum is 100 ms and context-switch is 1 ms
  - ▣ Now wasted time is only 1%
- But what if 50 concurrent requests come in?
  - ▣ Each with widely varying CPU requirements
  - ▣ 1<sup>st</sup> one starts immediately, 2<sup>nd</sup> one 100 ms later, ...
  - ▣ The last one may have to wait for 5 seconds!
  - ▣ A shorter quantum would have given them better service

# If quantum is set longer than mean CPU burst?

- **Preemption will not happen very often**
- Most processes will perform a blocking operation before quantum runs out
- Switches happens only when process blocks and cannot continue

# Quantum: Summarizing the possibilities

- Too short?
  - ▣ Too *many* context switches
  - ▣ *Lowers* CPU efficiency
- Too long?
  - ▣ *Poor* responses to interactive requests

# LOTTERY SCHEDULING

# Lottery scheduling

- Give processes **lottery tickets** for various system resources
  - ▣ E.g. CPU time
- When a scheduling decision has to be made
  - ▣ Lottery ticket is *chosen at random*
  - ▣ Process holding **ticket gets** the resource

# All processes are equal, but some processes are more equal than others

- More important processes are given **extra tickets**
  - ▣ Increase their odds of winning
- Let's say there are 100 outstanding tickets
  - ▣ 1 process holds 20 of these
  - ▣ Has 20% chance of winning each lottery
- A process holding a fraction  $f$  of tickets
  - ▣ Will get about a fraction  $f$  of the resource

# Lottery Scheduling: Properties

(1 / 2)

- Highly **responsive**
  - ▣ Chance of winning is proportional to tickets
- Cooperating processes may **exchange** tickets
  - ▣ Process **A** sends request to **B**, and then hands **B** all its tickets for a faster response
- Avoids starvation
  - ▣ Each process holds at least one ticket .... Is guaranteed to have a non-zero probability of being scheduled

# Lottery Scheduling: Properties

(2/2)

- Solves problems that are *difficult to handle* in other scheduling algorithms
- E.g. video server that is managing processes that feed video frames to clients
  - ▣ Clients need frames at 10, 20, and 25 frames/sec
  - ▣ Allocate processes 10, 20 and 25 tickets
    - CPU divided into approximately 10:20:25



# MULTIPROCESSOR/CORE ENVIRONMENTS

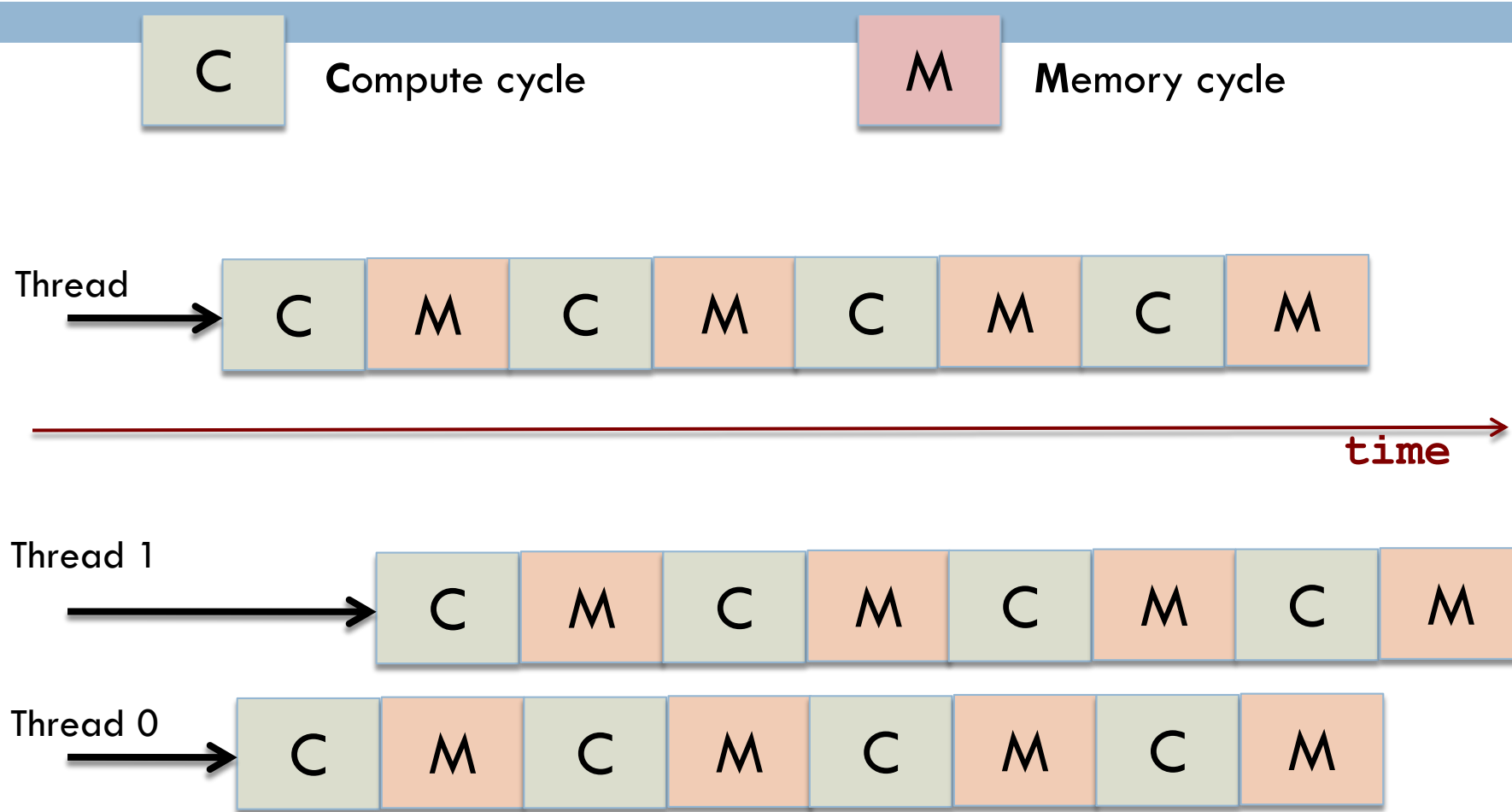
# Load balancing: Migration based approaches

- Push migration
  - ▣ Specific task periodically checks for *imbalance*
  - ▣ Balances load by **pushing** processes from overloaded to less-busy processors.
- Pull migration
  - ▣ Idle processor pulls a waiting task from busy processor
- Schemes **not mutually exclusive**: used in parallel
  - ▣ Linux: Runs a load-balancing algorithm
    - Every 200 ms (**PUSH** migration)
    - When processor run-queue is empty (**PULL** migration)

# Multicore processors place multiple processor cores on same physical chip

- Each core has its own register set
  - ▣ Appears to the OS as a separate physical processor
- Recent designs implement 2 or more hardware threads per core
  - ▣ If there is a memory stall (due to cache miss) on one thread, **switch** to another hardware thread

# Coping with memory stalls



# Multithreading a processor

- **Coarse** grained
  - ▣ Thread executes on processor till a memory stall
  - ▣ Switch to another thread
- Switching between threads
  - ▣ *Flush* the instruction pipeline
  - ▣ *Refill* pipeline as new thread executes
- **Finer** grained (or interleaved)
  - ▣ Switch between threads at the boundary of an instruction cycle
  - ▣ Design includes logic for thread switching: overheads are low

# Tiered scheduling on multicore processors

- First-level: OS
  - ▣ OS chooses which software thread to run on each hardware thread
- Second-level: Core
  - ▣ Decides which hardware thread to run
- UltraSPARC T1
  - ▣ 8 cores, and 4 hardware threads/core
  - ▣ Round robin to schedule hardware threads on core

# SCHEDULING EXAMPLES

# Scheduling examples

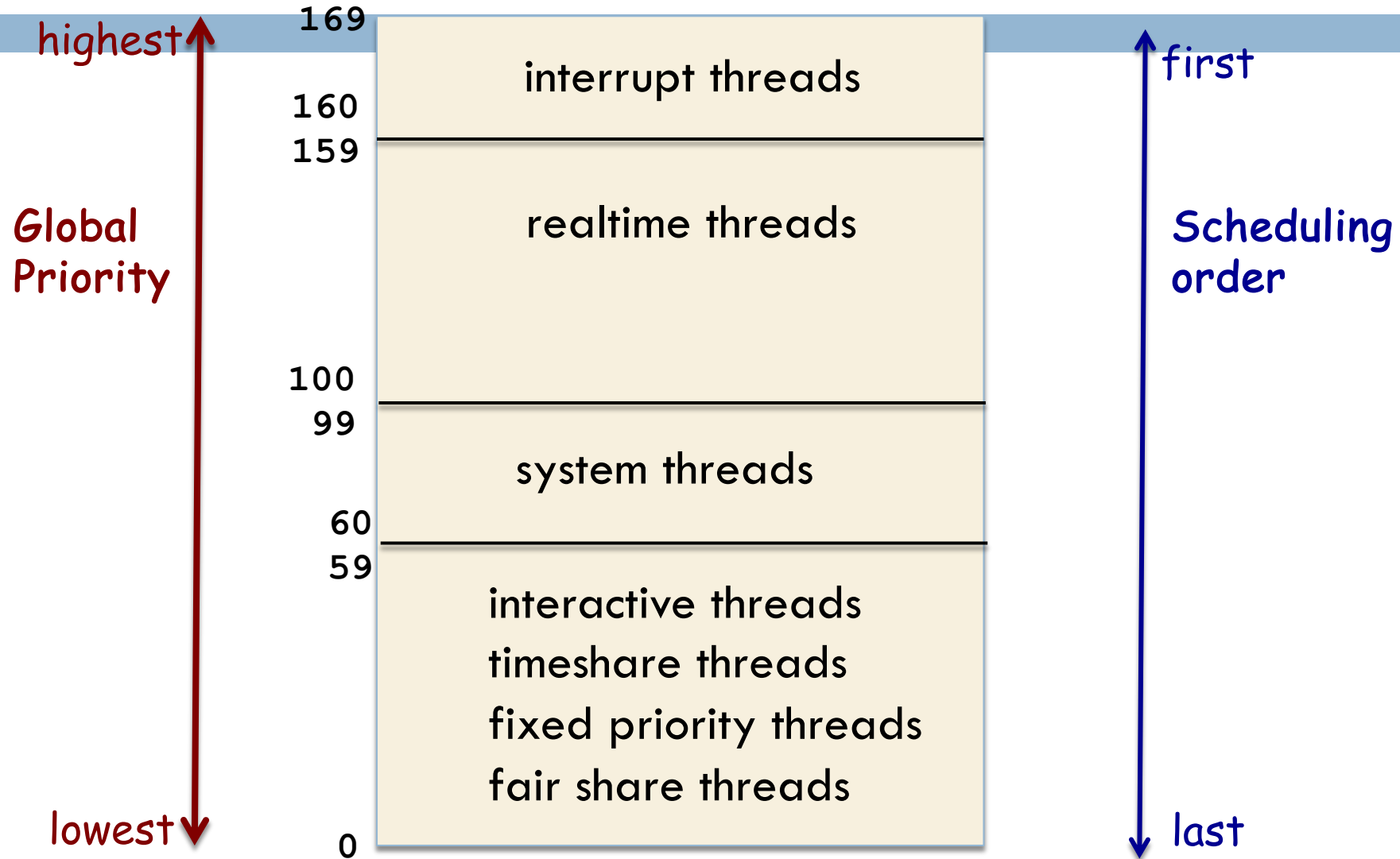
- Solaris
- Windows
- Linux



# Scheduling Example: Solaris

- Thread belongs to 1 of six classes
- **Inverse relationship** between priorities and time slices
  - ▣ Higher priority = smaller time slice
    - Interactive processes
    - Priority 59: 20 millisecond quantum
  - ▣ Lower priority = bigger time slice
    - CPU bound processes
    - Priority 0 = 200 millisecond quantum

# Solaris scheduling



# WINDOWS XP SCHEDULING

# Scheduling Example: Windows XP

- Priority-based, preemptive scheduling
  - ▣ Highest priority thread will always run
- 32-level priority scheme
  - ▣ Variable class: priorities 1-15
  - ▣ Realtime class: priorities 16-31
  - ▣ Memory management thread: priority 0

# Dispatcher in Windows XP

- Use a **queue** for each scheduling priority
- **Traverse** the queues from highest to lowest
  - ▣ *Until* it finds a thread that is ready to run
- If no ready thread is found?
  - ▣ Dispatcher will execute a special thread: **idle thread**

# Idle thread in Windows

- Primary purpose is to **eliminate a special case**
  - ▣ Cases when no threads are runnable or ready
  - ▣ Idle threads are always in a *ready* state
    - If not already running
- Scheduler can always find a thread to execute
- If there are other eligible threads?
  - ▣ Scheduler will never select the idle thread

# Idle threads in Windows

- Windows thread priorities go from 0-31
  - ▣ Idle thread priority can be thought of as -1
- Threads in the system idle process can also implement CPU power saving
  - ▣ On x86 processors, run a loop of **halt** instructions
  - ▣ Causes CPU to **turn off internal components**
    - Until an interrupt request arrives
  - ▣ Recent versions also **reduce the CPU clock speed**

# Time consumed by the idle process

- It may seem that the idle process is monopolizing the CPU
  - ▣ It is merely acting as a *placeholder during free time*
  - ▣ Proof that no other process wants that CPU time



# Scheduling Example: Windows XP

## Identifies **6 priority classes** for threads

- Thread priorities for classes are **variable**
- Relative priority for thread within a class

# Windows XP priorities: Threads within a priority class also have a relative priority

	REAL TIME	HIGH	ABOVE NORMAL	NORMAL	BELOW NORMAL	IDLE PRIORITY
Time-critical	31	15	15	15	15	15
highest	26	15	12	10	8	6
above normal	25	14	11	9	7	5
normal	24	13	10	8	6	4
below normal	23	12	9	7	5	3
lowest	22	11	8	6	4	2
idle	16	1	1	1	1	1

Base priority for each thread class

# Windows XP: Managing the priority of variable priority threads

- **Lowering** the priority of a thread
  - ▣ When a thread's quantum runs out
    - Lower priority BUT not below base priority

# Windows XP: Boosting the priority of threads

- Upon release from a **wait** operation
  - ▣ Thread waiting for keyboard IO gets big boost
  - ▣ Thread waiting for disk IO gets *moderate* boost
- Window with which user is **interacting**
  - ▣ Gives good response for interactive thread
- When process moves to **foreground**
  - ▣ Scheduling quantum boosted by 3

# LINUX SCHEDULING

# Highlights of Linux scheduling (1)

- Scheduling algorithm runs in constant time
- Implements real-time scheduling (POSIX 1.b)
  - ▣ Real-time tasks have static priorities
  - ▣ Other tasks have dynamic priorities
- We look at the algorithm in kernel version 2.5
  - ▣ Revised again in version 2.6.23 of the kernel [called: Completely Fair Scheduler]

# Highlights of Linux scheduling (2)

- Preemptive, priority-based algorithm
- Two separate priority ranges
  - ▣ **Real-time** range: 0-99
  - ▣ **Nice** value: 100-140
- Numerically *lower* values indicate *higher* priority

# Highlights of Linux scheduling (3)

- **UNLIKE** Solaris and Windows
  - ▣ Higher priority tasks = higher quanta
  - ▣ Lower priority tasks = lower quanta
- Task's **interactivity** determined by
  - ▣ *Sleeping times* waiting for I/O



# Task execution in Linux

- Task eligible for execution as long as it has time remaining in its time slice
- When a task has exhausted its time slice?
  - ▣ Ineligible for execution again, until ...
  - ▣ All other tasks have exhausted their time quanta

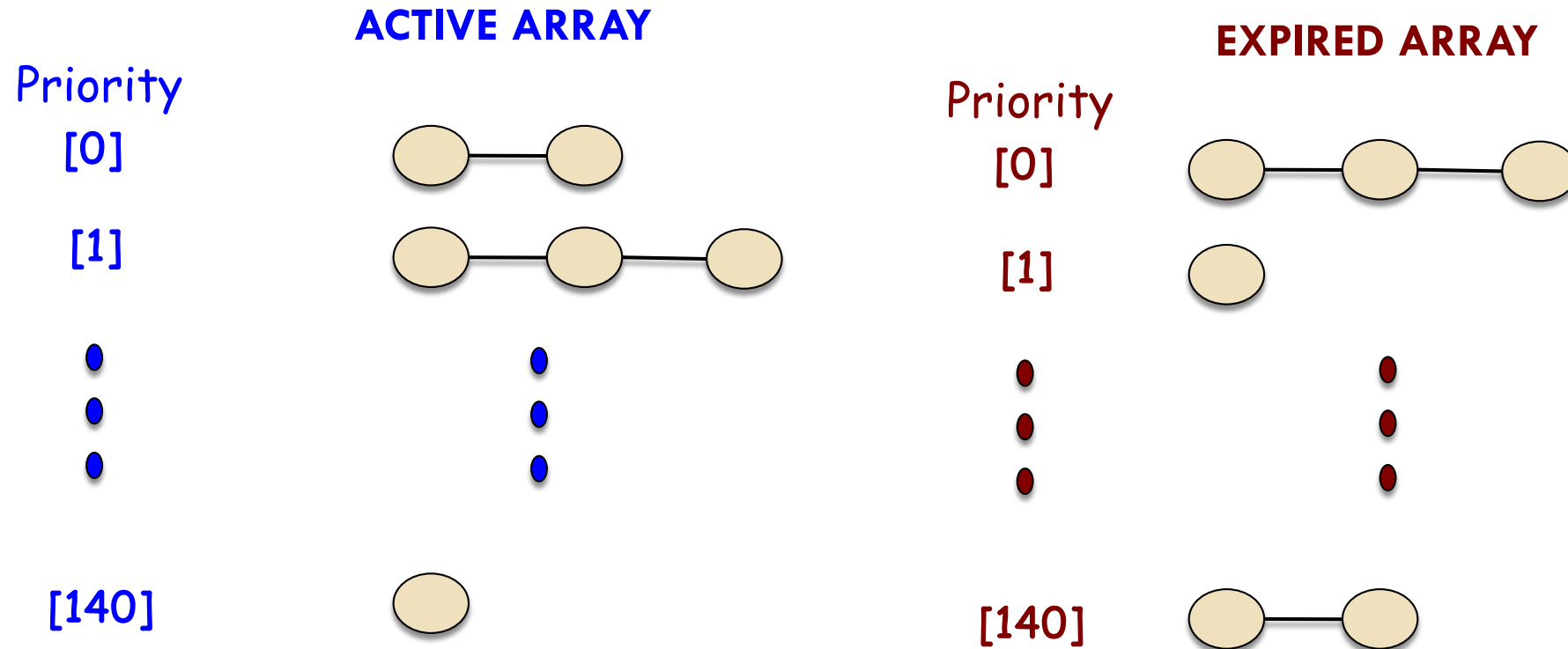
# Each `runqueue` contains two priority arrays: Active and Expired

- Active array
  - ▣ All tasks with time remaining in their time slices
- Expired array
  - ▣ Contains all expired tasks
- Each priority array contains list of tasks **indexed** according to priority

# Swapping the active and expired arrays

- When **all tasks have exhausted** their time slices?
  - ▣ Active array is empty
- The two priority arrays are **exchanged**
  - ▣ Expired array becomes the active array, and vice versa

# Linux: Tasks indexed according to priority



# Little's formula

- $n$  be the average queue length
- $W$  average wait time in the queue
- $\lambda$  average arrival rate of processes

When a process waits for time  $W$

$\lambda \times W$  processes arrives

Steady state: Processes leaving = Processes arriving

$$n = \lambda \times W$$

# The contents of this slide-set are based on the following references

- *Avi Silberschatz, Peter Galvin, Greg Gagne. Operating Systems Concepts, 9<sup>th</sup> edition. John Wiley & Sons, Inc. ISBN-13: 978-1118063330. [Chapter 6]*
- *Andrew S Tanenbaum and Herbert Bos. Modern Operating Systems. 4<sup>th</sup> Edition, 2014. Prentice Hall. ISBN: 013359162X/ 978-0133591620. [Chapter 2]*