

# CS 370: OPERATING SYSTEMS

## [ATOMIC TRANSACTIONS & DEADLOCKS]

Computer Science  
Colorado State University

Instructor: Louis-Noel Pouchet  
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\*\* Lecture slides created by: SHRIDEEP PALICKARA

# Topics covered in today's lecture

- Atomic Transactions
  - ▣ Locking protocols
  - ▣ Timestamp protocols
- Deadlocks
- Deadlock characterization

# LOCKING PROTOCOLS

# Locking protocol governs *how* locks are acquired and released

- There are different **modes** in which data can be locked
  - ▣ A transaction acquires a lock on a data item in different modes
- **Shared** mode locks
  - ▣  $T_i$  can read, but not write, data item  $Q$
- **Exclusive** mode locks
  - ▣  $T_i$  can read and write data item  $Q$

# Transactions must request locks on data items in the right mode

- To **access** data item  $Q$ ;  $T_i$  must first **lock** it
  - ▣ Wait if  $Q$  is locked in the exclusive mode
  - ▣ If  $T_i$  requests a shared-lock on  $Q$ 
    - Obtain lock if  $Q$  is not locked in the *exclusive* mode
- $T_i$  **must hold** lock on data item as long as it accesses it

# Two-phase locking protocol: Locks and unlocks take place in two phases

- Transaction's **growing** phase:
  - ▣ Obtain locks
  - ▣ *Cannot release* any lock
  
- Transaction's **shrinking** phase
  - ▣ Can release locks
  - ▣ *Cannot obtain* any new locks

# Two-phase locking protocol:

## Conflict serializability

- Conflicts occur when 2 transactions access same data item; and 1 of them is a write
- A transaction acquires locks serially; *without* releasing them during the acquire phase
  - ▣ Other transactions must wait for first transaction to start releasing locks.
- Deadlocks may occur

# Order of conflicting transactions

- Two-phase locking
  - ▣ Determined at **execution** time
- How about selecting this order in *advance*?
  - ▣ **Timestamp based protocols**



# Timestamp based protocols

- For each  $T_i$  there is a fixed timestamp
  - ▣ Denoted  $TS(T_i)$
  - ▣ Assigned before  $T_i$  starts execution
- For a later  $T_j$  ;  $TS(T_i) < TS(T_j)$
- Schedule must be equivalent to schedule in which  $T_i$  appears before  $T_j$ .

# Timestamp based locking

- Protocol ensures there will be **no deadlock**
  - ▣ No transaction ever waits!
- Conflict serializability
  - ▣ Conflicting operations are processed *in timestamp order*

# Each data item $Q$ has two values

- $W\text{-timestamp}(Q)$ 
  - ▣ Largest timestamp of any transaction that successfully executed `write()`
- $R\text{-timestamp}(Q)$ 
  - ▣ Largest timestamp of any transaction that successfully executed `read()`

# Transaction issues a read( $Q$ )

- If  $TS(T_i) < W\text{-timestamp}(Q)$ 
  - ▣ Needs value that was already **overwritten**
  - ▣ The read is rejected and  $T_i$  is rolled back
- $TS(T_i) \geq W\text{-timestamp}(Q)$ 
  - ▣ Operation is executed
  - ▣  $R\text{-timestamp}(Q) = \mathbf{max}(TS(T_i), R\text{-timestamp}(Q))$

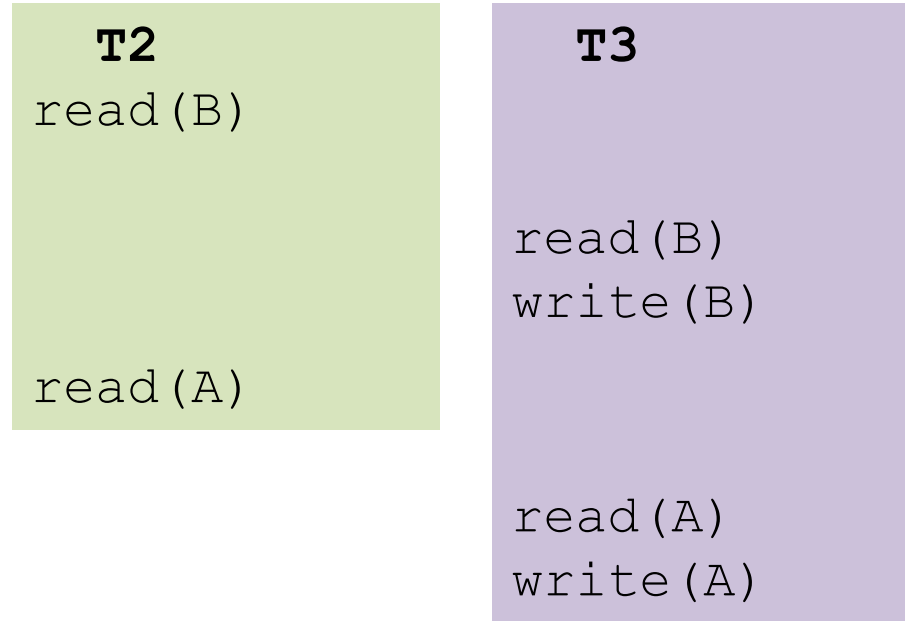
# Transaction issues a `write(Q)`

- If  $TS(T_i) < R\text{-timestamp}(Q)$ 
  - ▣ Value of `Q` produced by  $T_i$  needed *previously*
    - $T_i$  assumed that this value would never be produced
  - ▣ The `write` is rejected and  $T_i$  is rolled back
- If  $TS(T_i) < W\text{-timestamp}(Q)$ 
  - ▣ Trying to write an **obsolete** value of `Q`
  - ▣ The `write` is rejected and  $T_i$  is rolled back

# What happens when a transaction is rolled back?

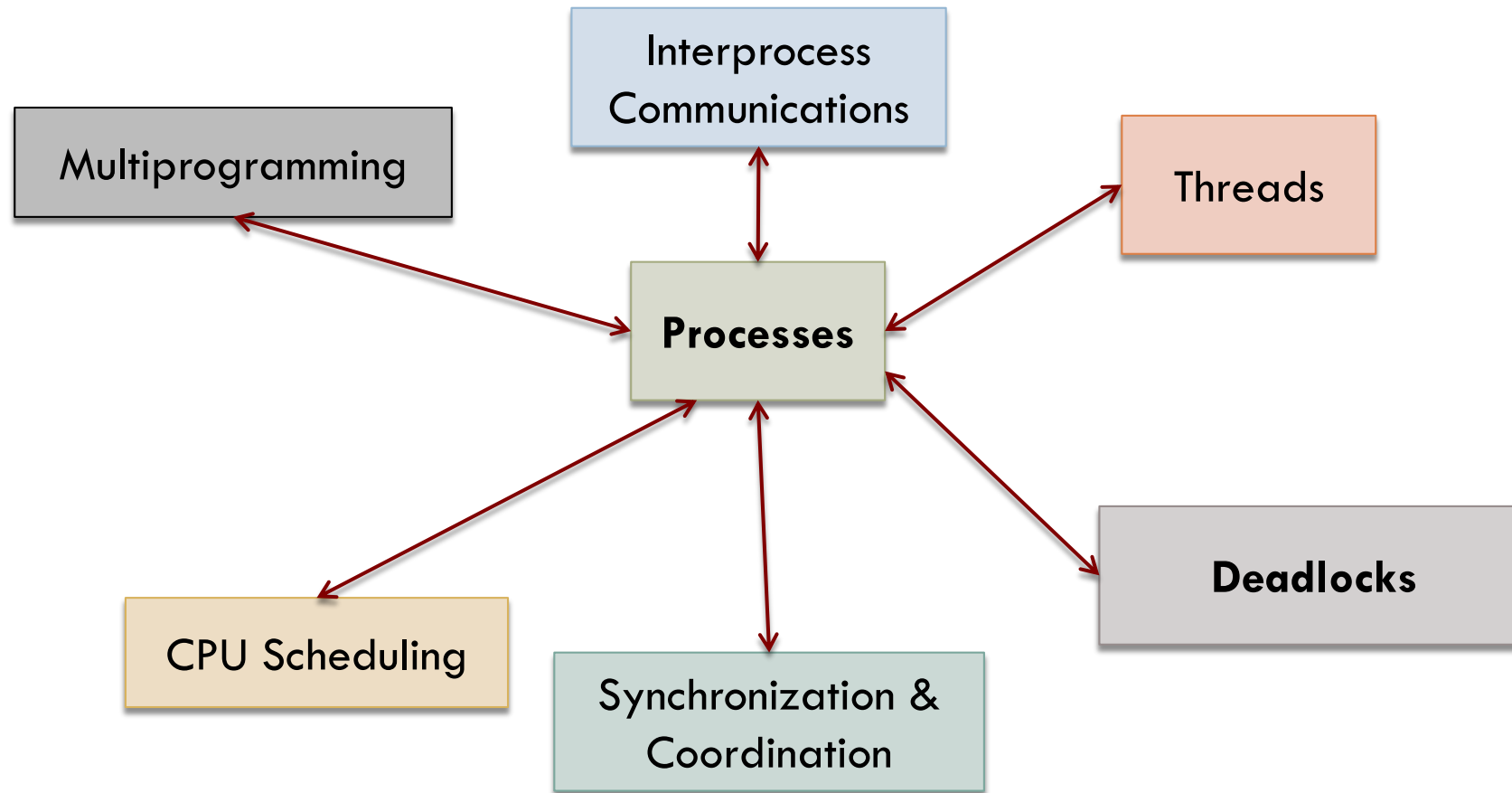
- Transactions  $T_i$  is assigned a new timestamp
  - ▣ Restart

# Schedule using the timestamp protocol:



Timestamps are assigned to transactions before  
the start of the first instruction  $TS(T2) < TS(T3)$

# The Journey So Far ...

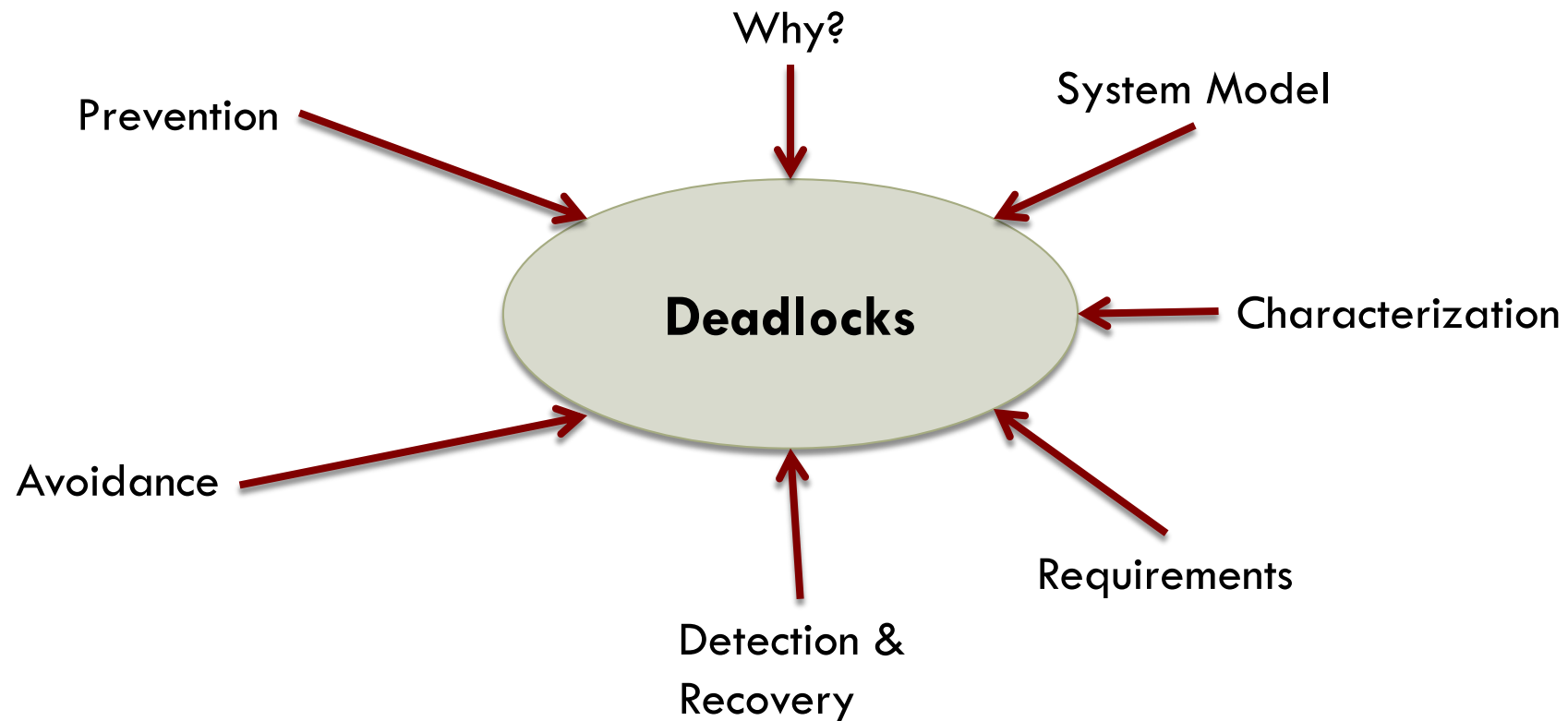




*A waiting process is never again able to change state  
It is waiting for resources held by other processes*

# DEADLOCKS

# What we will look at ...



# For many applications, processes need exclusive accesses to multiple resources

- Process A: Asks for scanner and is granted it
  - Process B: Asks CD recorder first and is granted it.
  - Process A: Now asks for CD recorder
  - Process B: Now asks for Scanner
- 
- Both processes are blocked and will remain so forever!
    - ▣ **Deadlock**

# Other deadlock situations

- Distributed systems involving multiple machines
- Database systems
  - ▣ Process 1 locks record R1
  - ▣ Process 2 locks record R2
  - ▣ Then, processes 1 and 2 try to lock each other's record
    - Deadlock
- **Deadlocks can occur in hardware or software resources**

# Resource Deadlocks

- Major class of deadlocks involves resources
  - ▣ Can occur when processes have been granted access to devices, data records, files, etc.
  - ▣ Other classes of deadlocks: communication deadlocks, two-phase locking
- Related concepts
  - ▣ Livelocks and starvation

# Preemptable resources

- Can be taken away from process owning it with no ill effects
- Example: Memory
  - ▣ Process **B**'s memory can be taken away and given to process **A**
    - Swap **B** from memory, write contents to backing store, swap **A** in and let it use the memory

# Non-preemptable resources

- Cannot be taken away from a process without causing the process to fail
- If a process has started to burn a CD
  - ▣ Taking the CD-recorder away from it and giving it to another process?
    - Garbled CD
    - CD recorders are not preemptable at an arbitrary moment
- In general, **deadlocks involve non-preemptable resources**

# Some notes on deadlocks

- The OS typically does not provide deadlock prevention facilities
- Programmers are *responsible* for designing deadlock free programs



# System model

- **Finite** number of resources
  - ▣ Distributed among *competing processes*
- Resources are *partitioned* into different **types**
  - ▣ Each *type* has a number of identical instances
  - ▣ Resource type examples:
    - Memory space, files, I/O devices

# A process must utilize resources in a sequence

## □ Request

- ▣ Requesting resource must *wait until it can acquire* resource
- ▣ `request()`, `open()`, `allocate()`

## □ Use

- ▣ Operate on the resource

## □ Release

- ▣ `release()`, `close()`, `free()`

# For kernel managed resources, the OS maintains a system resource table

- Is the resource free?
  - ▣ Record process that the resource is allocated to
- Is the resource allocated?
  - ▣ Add to queue of processes waiting for resource
- For resources not managed by the OS
  - ▣ Use `wait()` and `signal()` on semaphores

# Deadlock: Formal Definition

- *A set of processes is deadlocked if each process in the set is waiting for an event that only another process in the set can cause.*
- Because all processes are waiting, none of them can cause events to wake any other member of the set
  - ▣ Processes continue to **wait forever**

# DEADLOCK CHARACTERIZATION

# Deadlocks:

## Necessary Conditions (I)

### □ **Mutual Exclusion**

- ▣ At least one resource held in *nonsharable mode*
- ▣ When a resource is being used
  - Another requesting process must wait for its release

### □ **Hold-and-wait**

- ▣ A process must hold one resource
- ▣ Wait to acquire additional resources
  - Which are currently held by other processes

# Deadlocks:

## Necessary Conditions (II)

- **No preemption**

- Resources cannot be preempted
- Only voluntary release by process holding it

- **Circular wait**

- A set of  $\{P_0, P_1, \dots, P_n\}$  waiting processes must exist
  - $P_0 \rightarrow P_1; P_1 \rightarrow P_2, \dots, P_n \rightarrow P_0$
- Implies hold-and-wait

# Resource allocation graph

- Used to describe deadlocks precisely
- Consists of a set of vertices and edges
- Two different sets of nodes
  - $P$ : the set of all **active processes** in system
  - $R$ : the set of all **resource types** in the system



# Directed edges

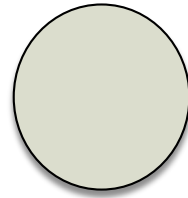
## □ **Request** edge

- $P_i$  has requested an instance of resource type  $R_j$
- Directed edge from process  $P_i$  to resource  $R_j$
- Denoted  $P_i \rightarrow R_j$
- *Currently waiting* for that resource

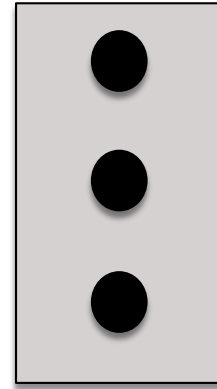
## □ **Assignment** edge

- Instance of resource  $R_j$  assigned to process  $P_i$
- Directed edge from resource  $R_j$  to process  $P_i$
- Denoted  $R_j \rightarrow P_i$

# Representation of Processes and Resources



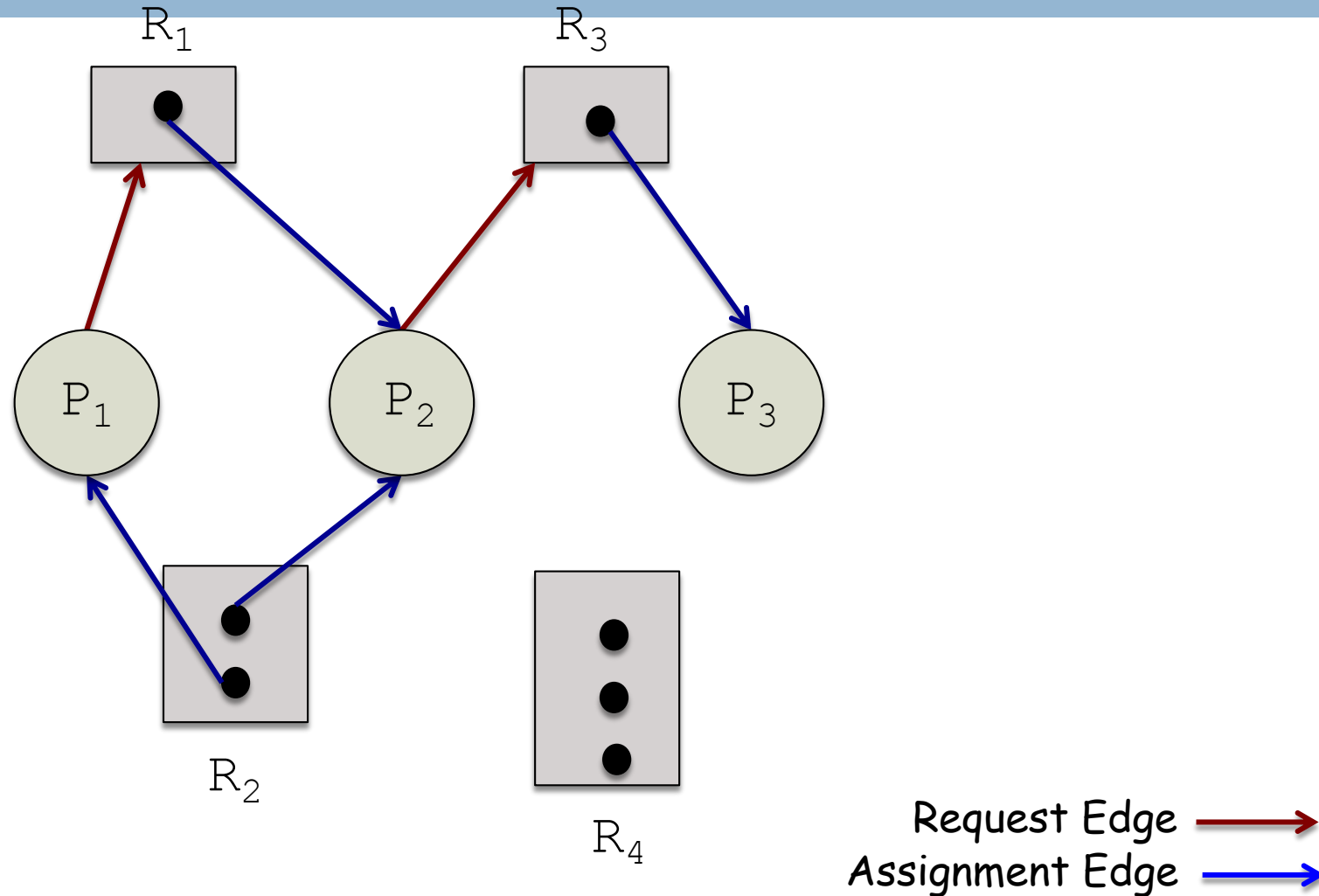
Processes



Resources

A resource type may have multiple instances

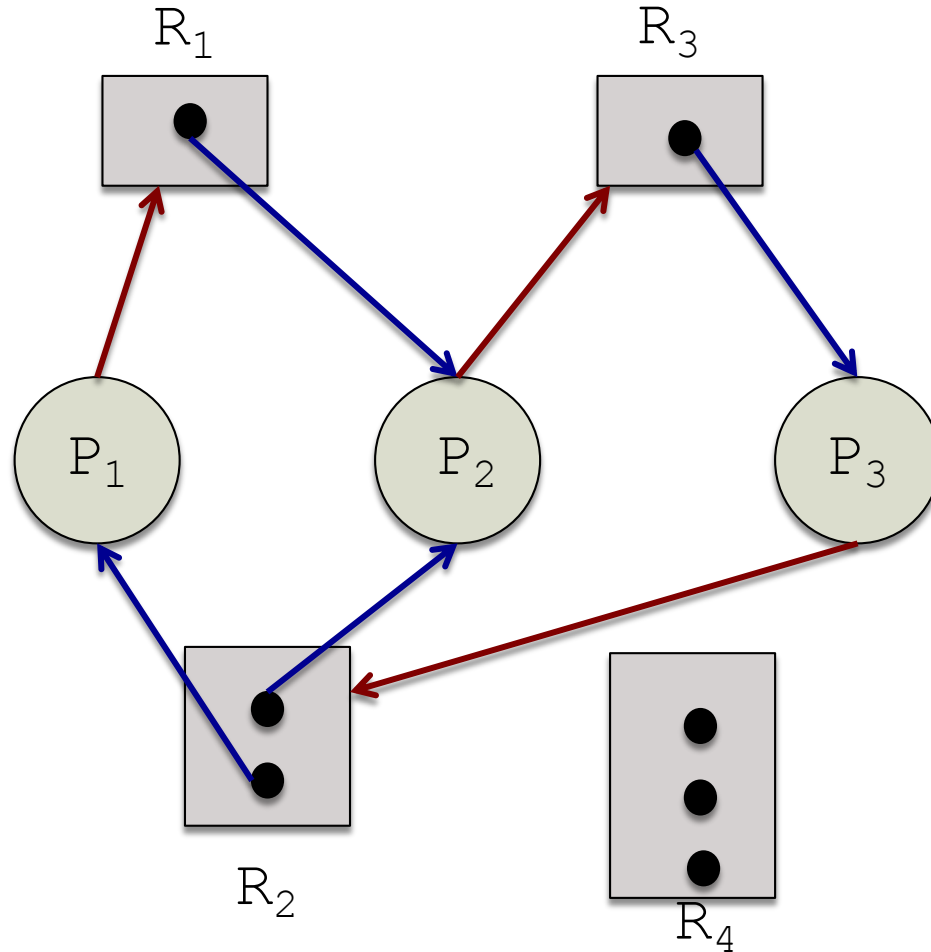
# Resource Allocation Graph example



# Determining deadlocks

- If the graph contains **no cycles**?
  - ▣ No process in the system is deadlocked
  
- If there is a **cycle** in the graph?
  - ▣ If each resource type has **exactly one** instance
    - Deadlock **has** occurred
  
  - ▣ If each resource type has **multiple** instances
    - A deadlock **may have** occurred

# Resource Allocation Graph: Deadlock example

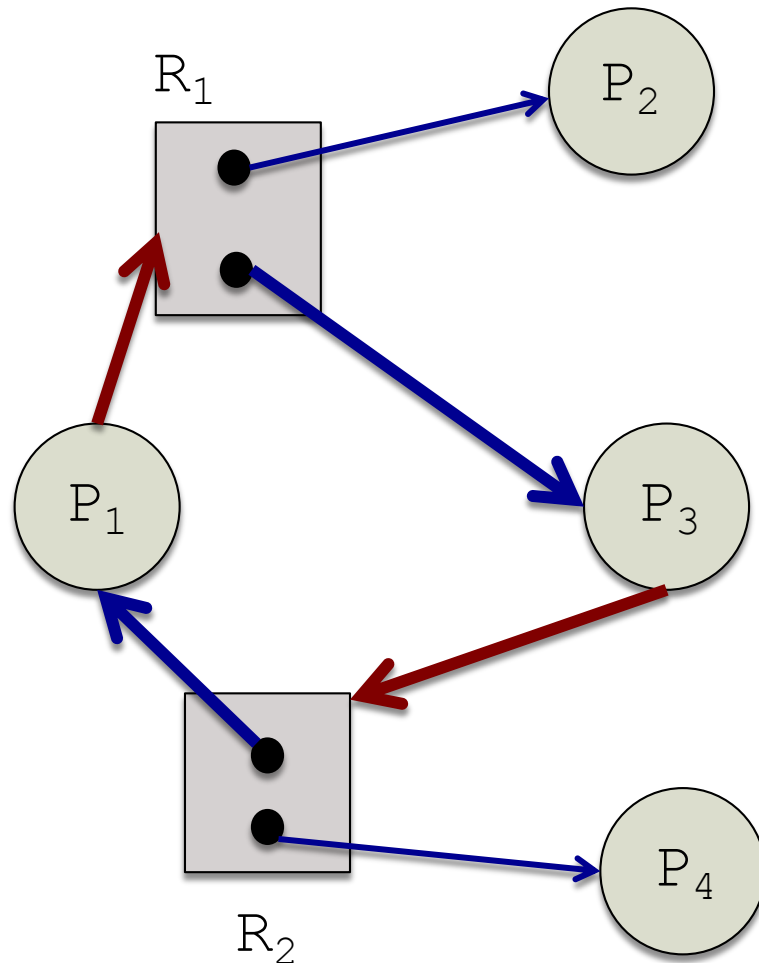


**Two cycles**

$P_1 \rightarrow R_1 \rightarrow P_2 \rightarrow R_3 \rightarrow P_3 \rightarrow R_2 \rightarrow P_1$

$P_2 \rightarrow R_3 \rightarrow P_3 \rightarrow R_2 \rightarrow P_2$

# Resource Allocation Graph: Cycle but not a deadlock



$P_1 \rightarrow R_1 \rightarrow P_3 \rightarrow R_2 \rightarrow P_1$

$P_4$  may release instance of  $R_2$   
allocate to  $P_3$  and break cycle

# Resource Allocation Graphs and Deadlocks

- If the graph does not have a cycle
  - ▣ No deadlock
- If the graph does have a cycle
  - ▣ System may or may not be deadlocked

# Methods for handling deadlocks

- Use protocol to **prevent** or **avoid** deadlocks
  - ▣ Ensure system never enters a deadlocked state
- Allow system to enter deadlocked state; BUT
  - ▣ **Detect** it and **recover**
- Ignore problem, pretend that deadlocks never occur



# Problems with undetected deadlocks

- Resources held by processes that cannot run
- More and more processes enter deadlocked state
  - ▣ When they request more resources
- **Deterioration** in system performance
  - ▣ Requires restart

# When is ignoring the problem viable?

- When they occur infrequently (once per year)
  - ▣ Ignoring is the *cheaper* solution
  - ▣ Prevention, avoidance, detection and recovery
    - Need to run constantly

# SOME DEADLOCK EXAMPLES

# Law passed by Kansas Legislature ... early 20<sup>th</sup> Century

*“When two trains approach each other at a crossing, both shall come to a full stop and neither shall start up again until the other has gone”*

# Dining philosophers problem:

## Necessary conditions for deadlock (1)

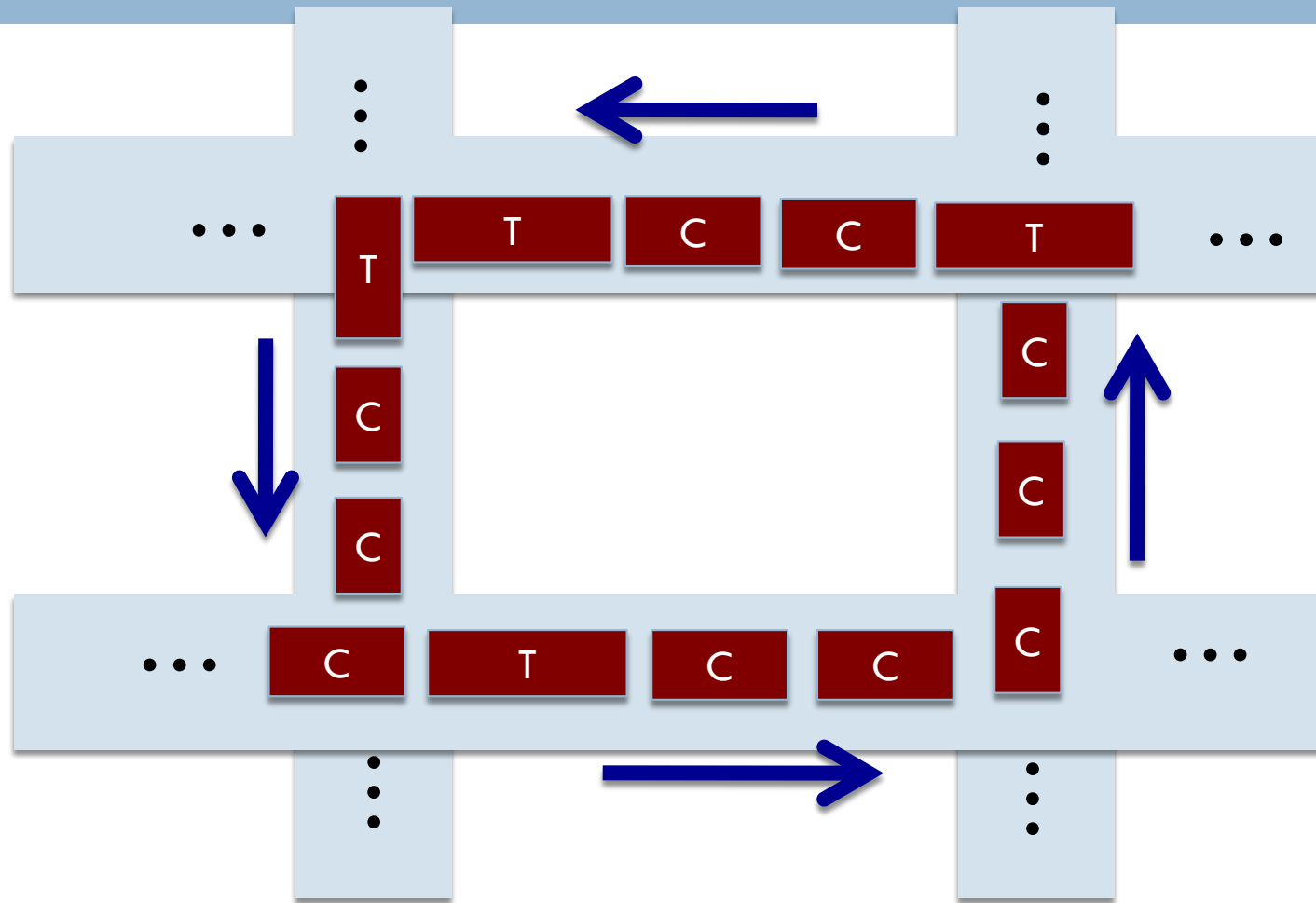
- Mutual exclusion
  - ▣ 2 philosophers *cannot share* the same chopstick
- Hold-and-wait
  - ▣ A philosopher *picks up one* chopstick at a time
  - ▣ Will not let go of the first while it *waits for the second* one

# Dining philosophers problem:

## Necessary conditions for deadlock (2)

- No preemption
  - ▣ A philosopher *does not snatch chopsticks* held by some other philosopher
- Circular wait
  - ▣ Could happen if each philosopher *picks chopstick with the same hand* first

# Is there a traffic deadlock here?



# The traffic scenario:

## Necessary Conditions (1)

- Mutual Exclusion
  - ▣ A vehicle needs its *own space*
  - ▣ We can't stack automobiles on top of each other
- Hold-and-wait
  - ▣ A vehicle does not move and *stays in place* if it cannot advance



# The traffic scenario:

## Necessary Conditions (2)

- No preemption
  - ▣ We *cannot move* an automobile to the side
- Circular-wait
  - ▣ Each vehicle is waiting for the one in front of it to advance

# DEALING WITH DEADLOCKS

# Four strategies for dealing with deadlocks

- Ignore the problem
  - ▣ May be if you ignore it, it will ignore you
- Detection and Recovery
  - ▣ Let deadlocks occur, detect them, and take action
- Deadlock avoidance
  - ▣ By careful resource allocation
- Deadlock prevention
  - ▣ By structurally negating one of the four required conditions

# The contents of this slide-set are based on the following references

- *Avi Silberschatz, Peter Galvin, Greg Gagne. Operating Systems Concepts, 9<sup>th</sup> edition. John Wiley & Sons, Inc. ISBN-13: 978-1118063330. [Chapter 5, 7]*
- *Andrew S Tanenbaum. Modern Operating Systems. 4<sup>th</sup> Edition, 2014. Prentice Hall. ISBN: 013359162X/ 978-0133591620. [Chapter 7]*