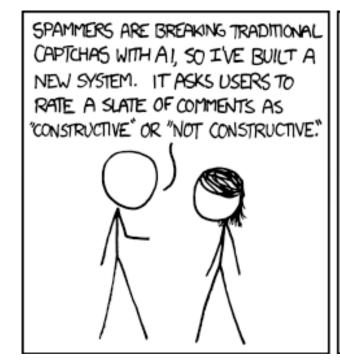
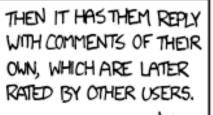
Linear models: Logistic regression

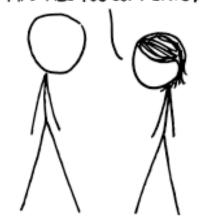
Chapter 3.3







BUT WHAT WILL YOU DO WHEN SPAMMERS TRAIN THEIR BOTS TO MAKE AUTOMATED CONSTRUCTIVE AND HELPRUL COMMENTS?





Predicting probabilities

Objective: learn to predict a probability $P(y \mid x)$ for a binary classification problem using a linear classifier

The target function:
$$\mathbb{P}[y = +1 \mid \mathbf{x}].$$

For positive examples $P(y = +1 \mid x) = 1$ whereas $P(y = +1 \mid x) = 0$ for negative examples.

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Can we assume that $P(y = +1 \mid x)$ is linear?

Logistic regression

The signal $s = \mathbf{w}^\mathsf{T} \mathbf{x}$ is the basis for several linear models:

linear classification

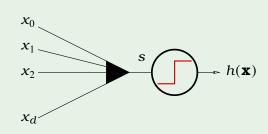
$$h(\mathbf{x}) = \operatorname{sign}(s)$$

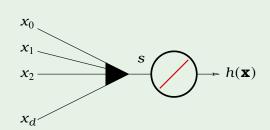
linear regression

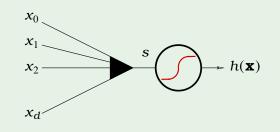
$$h(\mathbf{x}) = s$$

logistic regression

$$h(\mathbf{x}) = \theta(s)$$

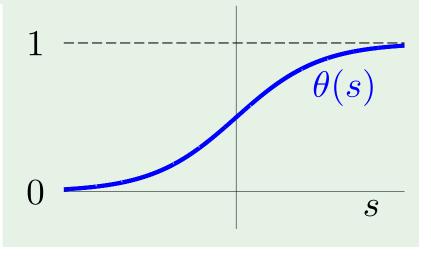






The logistic function (aka squashing function):

$$\theta(s) = \frac{e^s}{1 + e^s}$$



Properties of the logistic function

$$\theta(s) = \frac{e^s}{1 + e^s} = \frac{1}{1 + e^{-s}}.$$

$$\theta(-s) = \frac{e^{-s}}{1 + e^{-s}} = \frac{1}{1 + e^{s}} = 1 - \theta(s).$$



Predicting probabilities

Fitting the data means finding a good hypothesis h

$$h$$
 is good if:
$$\begin{cases} h(\mathbf{x}_n) \approx 1 & \text{whenever } y_n = +1; \\ h(\mathbf{x}_n) \approx 0 & \text{whenever } y_n = -1. \end{cases}$$

Suppose that $h(\mathbf{x}) = \theta(\mathbf{w}^T\mathbf{x})$ closely captures $\mathbb{P}[+1|\mathbf{x}]$:

$$P(y \mid \mathbf{x}) = \begin{cases} \theta(\mathbf{w}^{\mathsf{T}}\mathbf{x}) & \text{for } y = +1; \\ 1 - \theta(\mathbf{w}^{\mathsf{T}}\mathbf{x}) & \text{for } y = -1. \end{cases}$$

Predicting probabilities

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Suppose that $h(\mathbf{x}) = \theta(\mathbf{w}^T\mathbf{x})$ closely captures $\mathbb{P}[+1|\mathbf{x}]$:

$$P(y \mid \mathbf{x}) = \begin{cases} \theta(\mathbf{w}^{\mathsf{T}}\mathbf{x}) & \text{for } y = +1; \\ \theta(-\mathbf{w}^{\mathsf{T}}\mathbf{x}) & \text{for } y = -1. \end{cases}$$

More compactly:
$$P(y \mid \mathbf{x}) = \theta(y \cdot \mathbf{w}^{\mathrm{T}}\mathbf{x})$$

Is logistic regression really linear?

$$P(y = +1|\mathbf{x}) = \frac{\exp(\mathbf{w}^{\mathsf{T}}\mathbf{x})}{\exp(\mathbf{w}^{\mathsf{T}}\mathbf{x}) + 1}$$
$$P(y = -1|\mathbf{x}) = 1 - P(y = +1|\mathbf{x}) = \frac{1}{\exp(\mathbf{w}^{\mathsf{T}}\mathbf{x}) + 1}$$

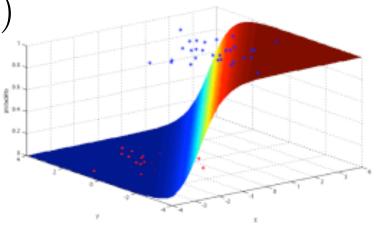
To figure out how the decision boundary looks like set

$$P(y = +1|\mathbf{x}) = P(y = -1|\mathbf{x})$$

solving for x we get:

$$\exp(\mathbf{w}^{\mathsf{T}}\mathbf{x}) = 1$$

i.e.
$$\mathbf{w}^{\mathsf{T}}\mathbf{x} = 0$$



Maximum likelihood

We will find w using the principle of maximum likelihood.

Likelihood:

The probability of getting the y_1, \ldots, y_N in \mathcal{D} from the corresponding $\mathbf{x}_1, \ldots, \mathbf{x}_N$:

$$P(y_1,\ldots,y_N\mid \mathbf{x}_1,\ldots,\mathbf{x}_n)=\prod_{n=1}^N P(y_n\mid \mathbf{x}_n).$$

Valid since $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$ are independently generated

Maximizing the likelihood

$$\max \qquad \prod_{n=1}^{N} P(y_n \mid \mathbf{x}_n)
\Leftrightarrow \max \qquad \ln \left(\prod_{n=1}^{N} P(y_n \mid \mathbf{x}_n) \right)
\equiv \max \qquad \sum_{n=1}^{N} \ln P(y_n \mid \mathbf{x}_n)
\Leftrightarrow \min \qquad -\frac{1}{N} \sum_{n=1}^{N} \ln P(y_n \mid \mathbf{x}_n)
\equiv \min \qquad \frac{1}{N} \sum_{n=1}^{N} \ln \frac{1}{P(y_n \mid \mathbf{x}_n)}
\equiv \min \qquad \frac{1}{N} \sum_{n=1}^{N} \ln \frac{1}{\theta(y_n \cdot \mathbf{w}^T \mathbf{x}_n)}
\equiv \min \qquad \frac{1}{N} \sum_{n=1}^{N} \ln (1 + e^{-y_n \cdot \mathbf{w}^T \mathbf{x}_n})$$

Maximizing the likelihood

Summary: maximizing the likelihood is equivalent to

minimize
$$E_{\mathrm{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \underbrace{\ln\left(1 + e^{-y_n \mathbf{w}^\mathsf{T} \mathbf{x}_n}\right)}_{\mathrm{e}\left(h(\mathbf{x}_n), y_n\right)}$$

Cross entropy error

Maximizing the likelihood

Summary: maximizing the likelihood is equivalent to

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$$E_{\mathrm{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \underbrace{\ln\left(1 + e^{-y_n \mathbf{w}^\mathsf{T} \mathbf{x}_n}\right)}_{\mathrm{e}\left(h(\mathbf{x}_n), y_n\right)}$$

Cross entropy error

Exercise: check that this is equivalent to:

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} I(y_n = +1) \ln \frac{1}{h(\mathbf{x}_n)} + I(y_n = -1) \ln \frac{1}{1 - h(\mathbf{x}_n)}$$

Digression: information theory

I am thinking of an integer between 0 and 1,023. You want to guess it using the fewest number of questions.

Most of us would ask "is it between 0 and 512?"

This is a good strategy because it provides the most information about the unknown number.

It provides the first binary digit of the number.

Initially you need to obtain $log_2(1024) = 10$ bits of information. After the first question you only need $log_2(512) = 9$ bits.

Information and Entropy

By halving the search space we obtained one bit.

In general, the information associated with a probabilistic outcome:

$$I(p) = -\log p$$

Why the logarithm?

Assume we have two independent events x, and y. We would like the information they carry to be additive. Let's check:

$$I(x,y) = -\log P(x,y) = -\log P(x)P(y)$$

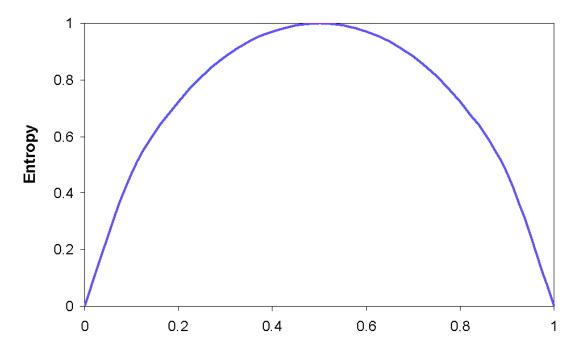
= $-\log P(x) - \log P(y) = I(x) + I(y)$

Entropy:
$$H(P) = -\sum_{x} P(x) \log P(x)$$

Entropy

For a Bernoulli random variable:

$$H(p) = -p \log p - (1 - p) \log(1 - p)$$



Maximal when $p = \frac{1}{2}$.

KL divergence

The KL divergence between distributions P and Q:

$$D_{KL}(P||Q) = -\sum_{x} P(x) \log \frac{Q(x)}{P(x)}$$

Properties:

- Non-negative, equal to 0 iff P = Q
- ♦ It is not symmetric

KL divergence

The KL divergence between distributions P and Q:

$$D_{KL}(P||Q) = -\sum_{x} P(x) \log \frac{Q(x)}{P(x)}$$

$$D_{KL}(P||Q) = -\sum_{x} P(x) \log Q(x) + \sum_{x} P(x) \log P(x)$$

cross entropy

- entropy

Cross entropy and logistic regression

The logistic regression cost function:

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} I(y_n = +1) \ln \frac{1}{h(\mathbf{x}_n)} + I(y_n = -1) \ln \frac{1}{1 - h(\mathbf{x}_n)}$$

It is the average cross entropy between the learned $P(y \mid x)$ and the observed probabilities

Cross entropy
$$H(P,Q) = -\sum_x P(x) \log Q(x)$$

And for binary variables:

$$H(y, \hat{y}) = -y \log \hat{y} - (1 - y) \log(1 - \hat{y})$$

In-sample error

The in-sample error for logistic regression

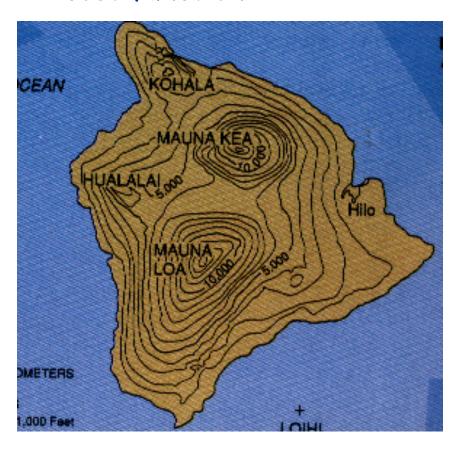
minimize
$$E_{\mathrm{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \underbrace{\ln\left(1 + e^{-y_n \mathbf{w}^\mathsf{T} \mathbf{x}_n}\right)}_{\mathrm{e}\left(h(\mathbf{x}_n), y_n\right)}$$

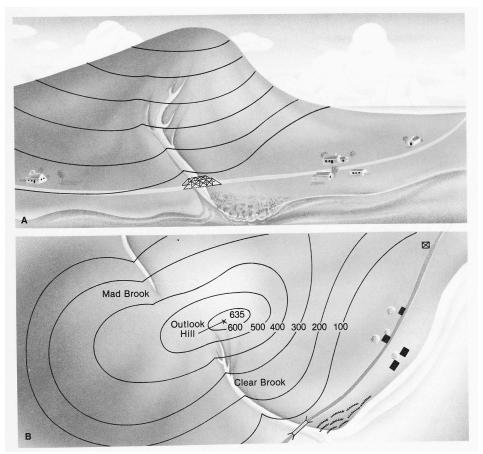
Cross entropy error

$$\nabla E_{\text{in}} = -\frac{1}{N} \sum_{n=1}^{N} \frac{y_n \mathbf{x}_n}{1 + e^{y_n \mathbf{w}^\mathsf{T}} \mathbf{x}_n}$$

Digression: gradient ascent/descent

Topographical maps can give us intuition on how to optimize a cost function



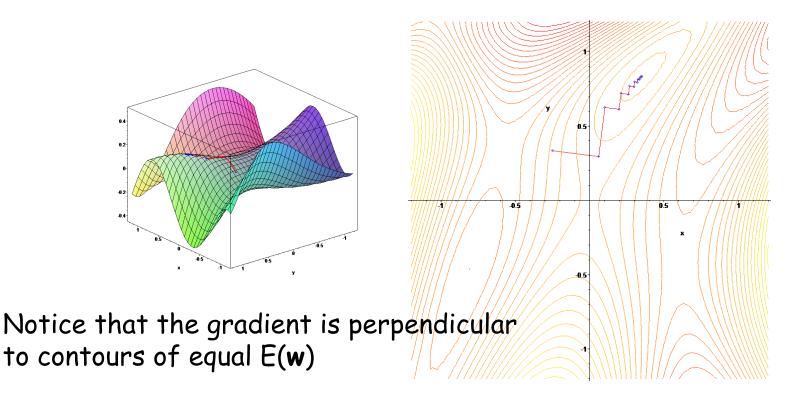


http://www.csus.edu/indiv/s/slaymaker/archives/geol10l/shield1.jpg

http://www.sir-ray.com/touro/IMG_0001_NEW.jpg

Digression: gradient descent

Given a function $E(\mathbf{w})$, the gradient is the direction of steepest ascent Therefore to minimize $E(\mathbf{w})$, take a step in the direction of the negative of the gradient

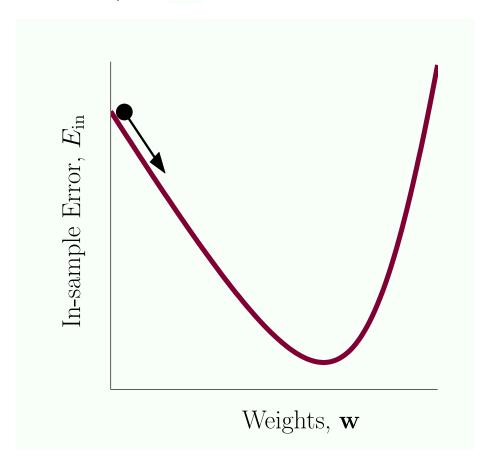


Gradient descent

Gradient descent is an iterative process

$$\mathbf{w}(t+1) = \mathbf{w}(t) + \eta \hat{\mathbf{v}}$$

How to pick $\hat{\mathbf{v}}$?



Gradient descent

The gradient is the best direction to take to optimize $E_{in}(\mathbf{w})$:

$$\Delta E_{\text{in}} = E_{\text{in}}(\mathbf{w}(t+1)) - E_{\text{in}}(\mathbf{w}(t))$$

$$= E_{\text{in}}(\mathbf{w}(t) + \eta \hat{\mathbf{v}}) - E_{\text{in}}(\mathbf{w}(t))$$

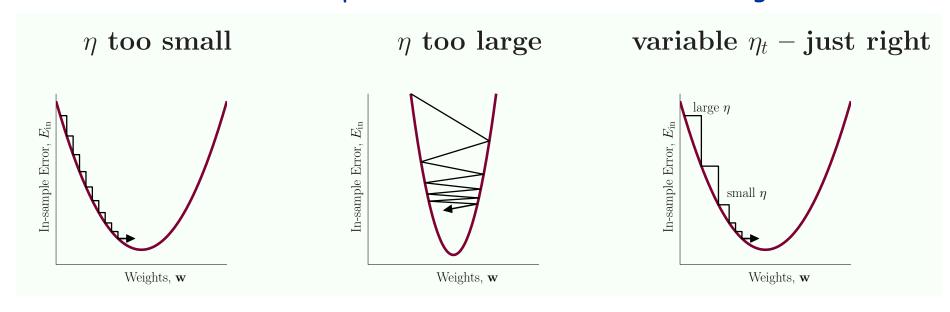
$$= \eta \nabla E_{\text{in}}(\mathbf{w}(t))^{T} \hat{\mathbf{v}} + O(\eta^{2})$$

$$= \eta \nabla E_{\text{in}}(\mathbf{w}(t))^{T} \hat{\mathbf{v}} + O(\eta^{2})$$

$$= \frac{\nabla E_{\text{in}}(\mathbf{w}(t))}{\|\nabla E_{\text{in}}(\mathbf{w}(t))\|}$$

Choosing the step size

The choice of the step size affects the rate of convergence:



Let's use a variable learning rate:

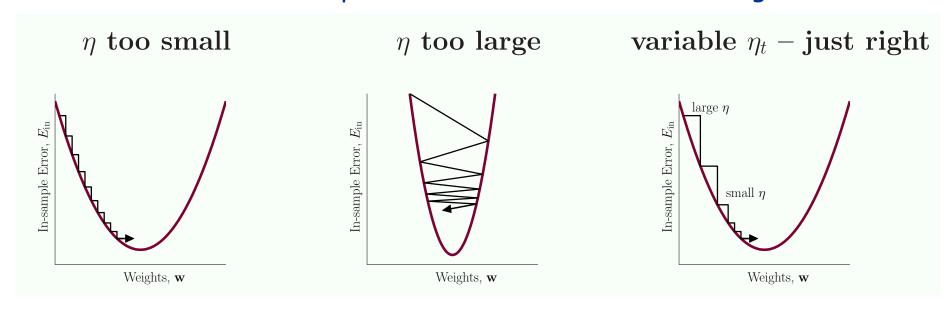
$$\mathbf{w}(t+1) = \mathbf{w}(t) + \eta_t \hat{\mathbf{v}}$$
$$\eta_t = \eta \cdot ||\nabla E_{\text{in}}(\mathbf{w}(t))||$$

When approaching the minimum:

$$||\nabla E_{\rm in}(\mathbf{w}(t))|| \to 0$$

Choosing the step size

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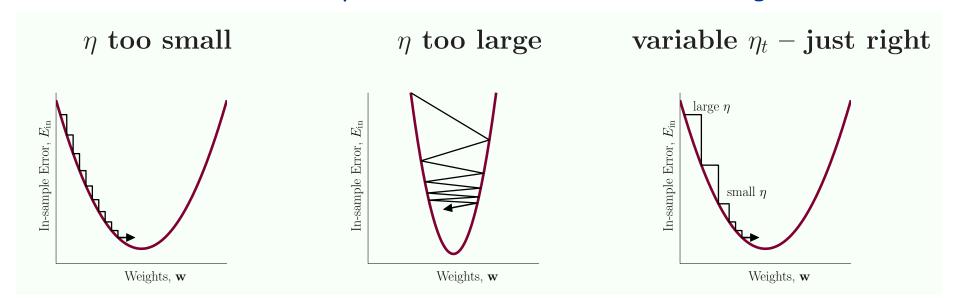
$$\mathbf{w}(t+1) = \mathbf{w}(t) + \eta_t \hat{\mathbf{v}}$$

$$\eta_t = \eta \cdot ||\nabla E_{\rm in}(\mathbf{w}(t))||$$

$$\eta_t \hat{\mathbf{v}} = -\eta \cdot ||\nabla E_{\text{in}}(\mathbf{w}(t))|| \cdot \frac{\nabla E_{\text{in}}(\mathbf{w}(t))}{||\nabla E_{\text{in}}(\mathbf{w}(t))||} = -\eta \nabla E_{\text{in}}(\mathbf{w}(t))$$

The final form of gradient descent

The choice of the step size affects the rate of convergence:

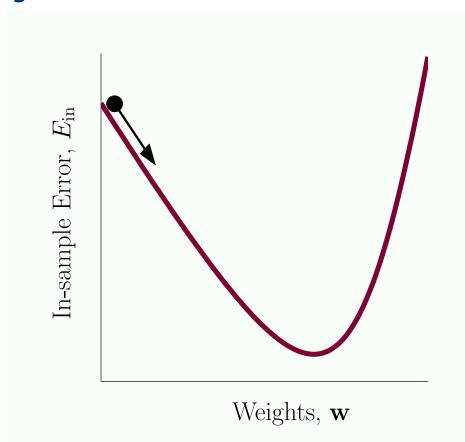


$$\mathbf{w}(t+1) = \mathbf{w}(t) - \eta \nabla E_{\text{in}}(\mathbf{w}(t))$$

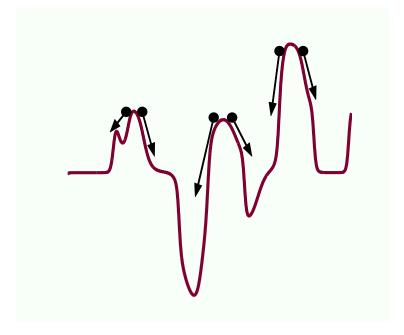
Logistic regression using gradient descent

We will use gradient descent to minimize our error function.

Fortunately, the logistic regression error function has a single global minimum:



So we don't need to worry about getting stuck in local minima



Logistic regression using gradient descent

Putting it all together:

- 1: Initialize at step t = 0 to $\mathbf{w}(0)$.
- 2: **for** $t = 0, 1, 2, \dots$ **do**
- 3: Compute the gradient

$$\mathbf{g}_t = \nabla E_{\text{in}}(\mathbf{w}(t)).$$

- 4: Move in the direction $\mathbf{v}_t = -\mathbf{g}_t$.
- 5: Update the weights:

$$\mathbf{w}(t+1) = \mathbf{w}(t) + \eta \mathbf{v}_t.$$

- 6: Iterate 'until it is time to stop'.
- 7: end for
- 8: Return the final weights.

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \underbrace{\ln\left(1 + e^{-y_n \mathbf{w}^{\mathsf{T}} \mathbf{x}_n}\right)}_{e(h(\mathbf{x}_n), y_n)}$$

$$\nabla E_{\text{in}} = -\frac{1}{N} \sum_{n=1}^{N} \frac{y_n \mathbf{x}_n}{1 + e^{y_n \mathbf{w}^{\mathsf{T}}(t) \mathbf{x}_n}}$$

This is called batch gradient descent

Logistic regression

Comments:

- In practice logistic regression is solved by faster methods than gradient descent
- * There is an extension to multi-class classification

Stochastic gradient descent

Variation on gradient descent that considers the error for a single training example:

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \ln(1 + e^{-y_n \cdot \mathbf{w}^{\mathsf{T}} \mathbf{x}}) = \frac{1}{N} \sum_{n=1}^{N} e(\mathbf{w}, \mathbf{x}_n, y_n)$$

Pick a random data point (\mathbf{x}_*, y_*)

Run an iteration of GD on $e(\mathbf{w}, \mathbf{x}_*, y_*)$

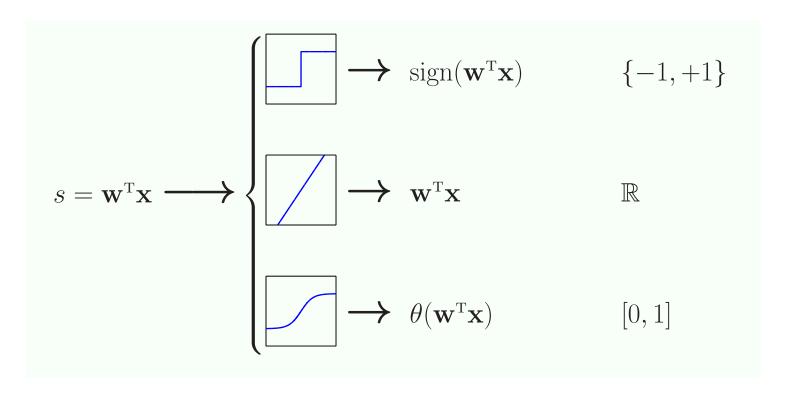
$$\mathbf{w}(t+1) \leftarrow \mathbf{w}(t) - \eta \nabla_{\mathbf{w}} e(\mathbf{w}, \mathbf{x}_*, y_*)$$

$$\mathbf{w}(t+1) \leftarrow \mathbf{w}(t) + \mathbf{y}_* \mathbf{x}_* \left(\frac{\eta}{1 + e^{y_* \mathbf{w}^{\mathrm{T}} \mathbf{x}_*}} \right)$$

Tends to converge faster than the batch version.

Summary of linear models

Linear methods for classification and regression:



More to come!