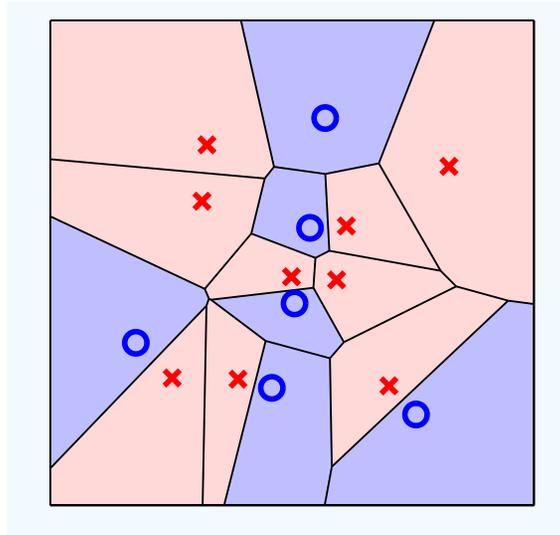

Nearest neighbor classifiers

Chapter e-6



Nearest Neighbor Classification

$NN(\text{image})$:

1. Find the image in the training data which is closest to the query image.
2. Return its label.



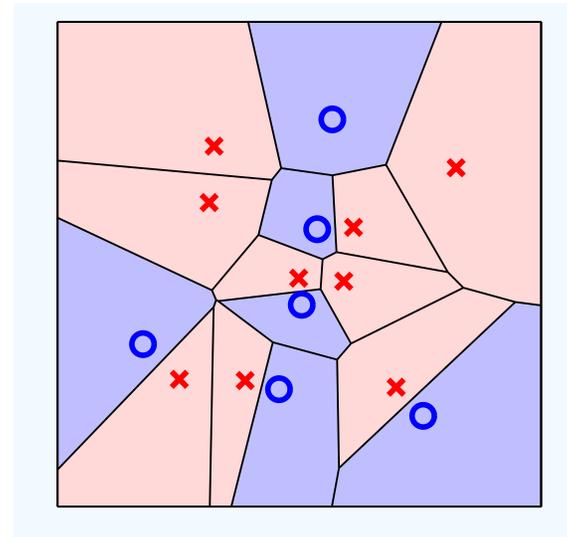
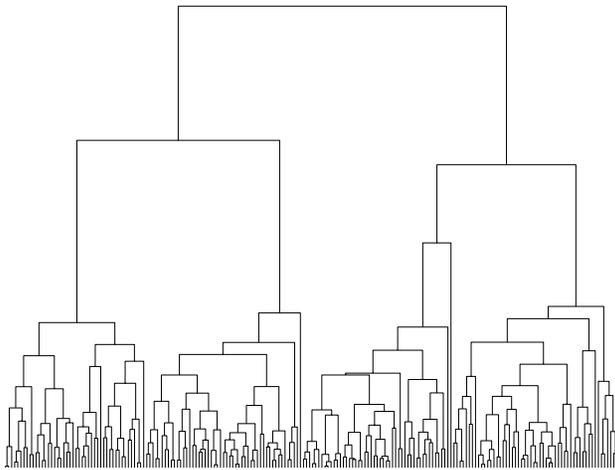
query



closest image

Distance based methods

- Supervised learning methods (nearest neighbor methods)
- Clustering (k-means and hierarchical clustering)



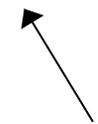
Measuring distance

How to measure closeness?

Distance measures for continuous data:

The Euclidean distance:

$$d_2(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_2 = \sqrt{(\mathbf{x} - \mathbf{x}')^\top (\mathbf{x} - \mathbf{x}')} = \sqrt{\sum_{i=1}^d (x_i - x'_i)^2}$$



(based on the 2-norm)

More distance measures

The Manhattan distance:

$$d_1(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_1 = \sum_{i=1}^d |x_i - x'_i|$$

This is the distance if we can only travel along coordinate axes.

The Minkowski distance

The **Minkowski** distance of order p :

$$d_p(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_p = \left(\sum_{i=1}^d |x_i - x'_i|^p \right)^{1/p}$$

This is based on the p -norm (sometimes called the L_p norm).

The Euclidean and Manhattan distances are special cases

The Minkowski distance

The **Minkowski** distance of order p :

$$d_p(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_p = \left(\sum_{i=1}^d |x_i - x'_i|^p \right)^{1/p}$$

This is based on the p -norm (sometimes called the L_p norm).

What happens when p goes to infinity?

The Minkowski distance

The **Minkowski** distance of order p :

$$d_p(\mathbf{x}, \mathbf{x}') = \|\mathbf{x} - \mathbf{x}'\|_p = \left(\sum_{i=1}^d |x_i - x'_i|^p \right)^{1/p}$$

What happens when p goes to infinity?

$$d_\infty(\mathbf{x}, \mathbf{x}') = \max_i |x_i - x'_i|$$

We get the **Chebyshev** distance

	a	b	c	d	e	f	g	h	
8	5	4	3	2	2	2	2	2	8
7	5	4	3	2	1	1	1	2	7
6	5	4	3	2	1	♔	1	2	6
5	5	4	3	2	1	1	1	2	5
4	5	4	3	2	2	2	2	2	4
3	5	4	3	3	3	3	3	3	3
2	5	4	4	4	4	4	4	4	2
1	5	5	5	5	5	5	5	5	1
	a	b	c	d	e	f	g	h	

image from https://en.wikipedia.org/wiki/Chebyshev_distance

The Minkowski distance

The unit sphere for various values of p

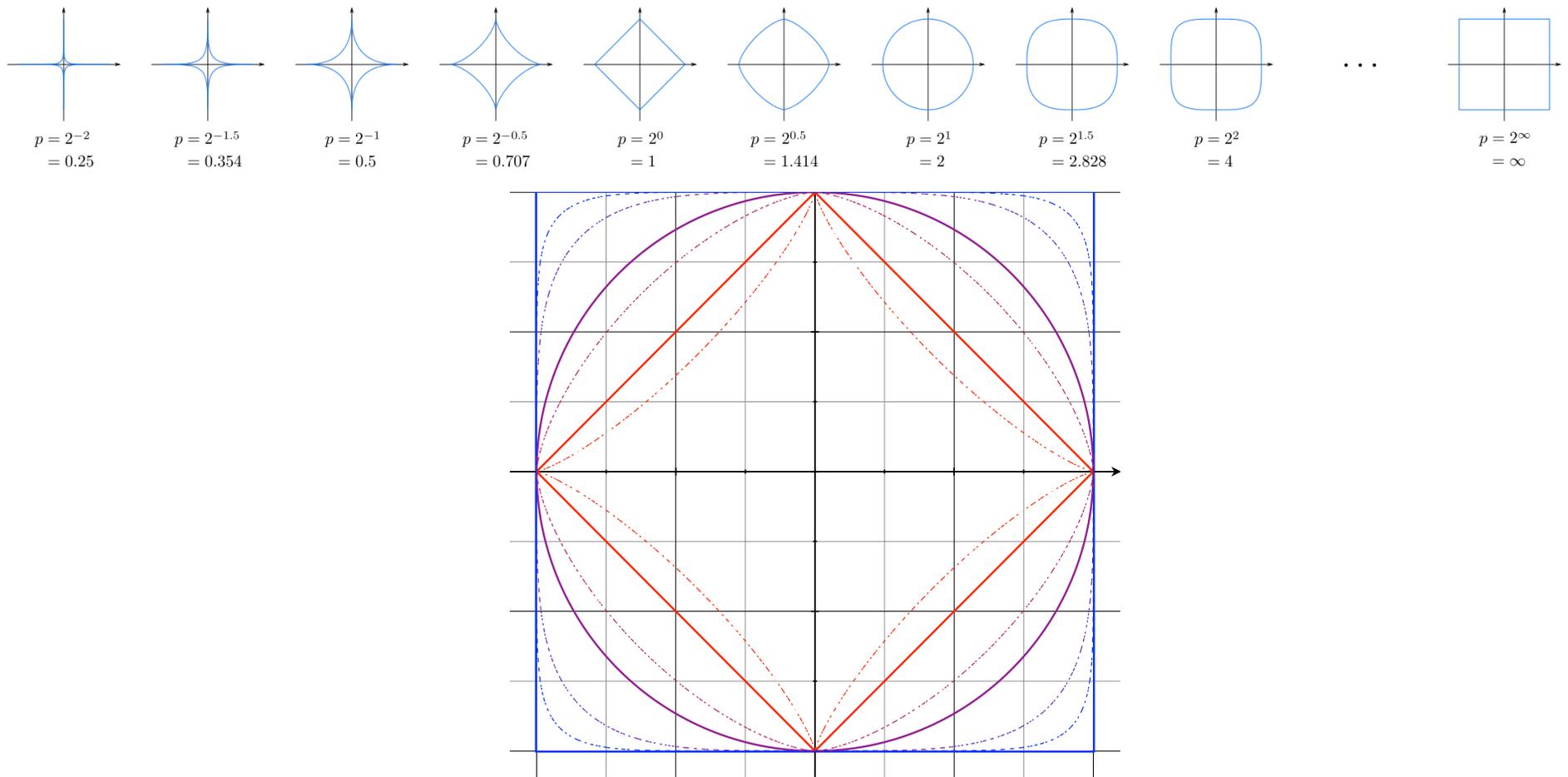


image from https://en.wikipedia.org/wiki/Minkowski_distance

Properties of a distance

A function $d(\mathbf{x}, \mathbf{x}')$ is called a distance function if it satisfies the following conditions:

- i. $d(\mathbf{x}, \mathbf{x}) = 0$ (a distance of a point to itself is zero)
- ii. $d(\mathbf{x}, \mathbf{x}') \neq 0$ if $\mathbf{x} \neq \mathbf{x}'$ (all other distances are non-zero)
- iii. $d(\mathbf{x}, \mathbf{x}') = d(\mathbf{x}', \mathbf{x})$ (distances are symmetric)
- iv. $d(\mathbf{x}, \mathbf{x}') \leq d(\mathbf{x}, \mathbf{x}'') + d(\mathbf{x}'', \mathbf{x}')$ (detours make distances larger)

The last condition is called the **triangle inequality**

The Minkowski distance with $p < 1$ does not satisfy the triangle inequality.

Data normalization

Is very important in this context!

The Mahalanobis distance

Sometimes it's useful to use different scales for different coordinates.

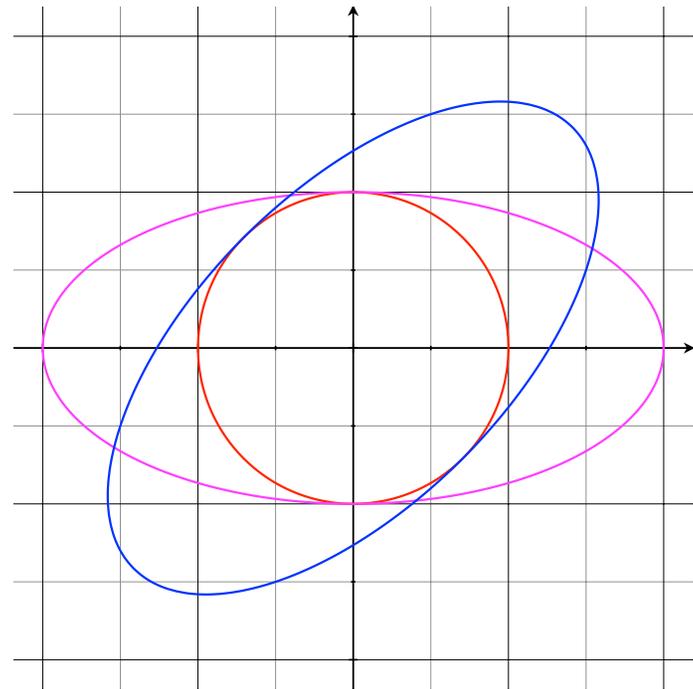
Therefore: use an ellipse rather than a circle to identify points that are a fixed distance away.

Also consider rotating the ellipse.

$$\mathbf{R} = \begin{pmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{pmatrix}$$

45 degree clockwise rotation

$$\mathbf{S} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & 1 \end{pmatrix}$$



$\mathbf{x}^T \mathbf{R}^T \mathbf{S}^2 \mathbf{R} \mathbf{x} = 1/4$; the axis-parallel ellipse $\mathbf{x}^T \mathbf{S}^2 \mathbf{x} = 1/4$; and the circle $\mathbf{x}^T \mathbf{x} = 1/4$.

The Mahalanobis distance

The shape of the ellipse can be estimated from data as the inverse of the covariance matrix:

$$Dis_M(\mathbf{x}, \mathbf{y} | \Sigma) = \sqrt{(\mathbf{x} - \mathbf{y})^\top \Sigma^{-1} (\mathbf{x} - \mathbf{y})}$$

(The inverse of the covariance matrix has the effect of decorrelating and normalizing features)

Nearest neighbor classification

$NN(\text{image})$:

1. Find the image in the training data which is closest to the query image.
2. Return its label.



query



closest image

Nearest neighbor classification

The nearest neighbor classifier:

Classify a given test example to the class of the nearest training example.

More formally:

$$\mathcal{D} = (\mathbf{x}_1, y_1) \dots (\mathbf{x}_N, y_N)$$

Reorder the data according to its similarity to an input \mathbf{x} :

$$(\mathbf{x}_{[n]}(\mathbf{x}), y_{[n]}(\mathbf{x}))$$

i.e.

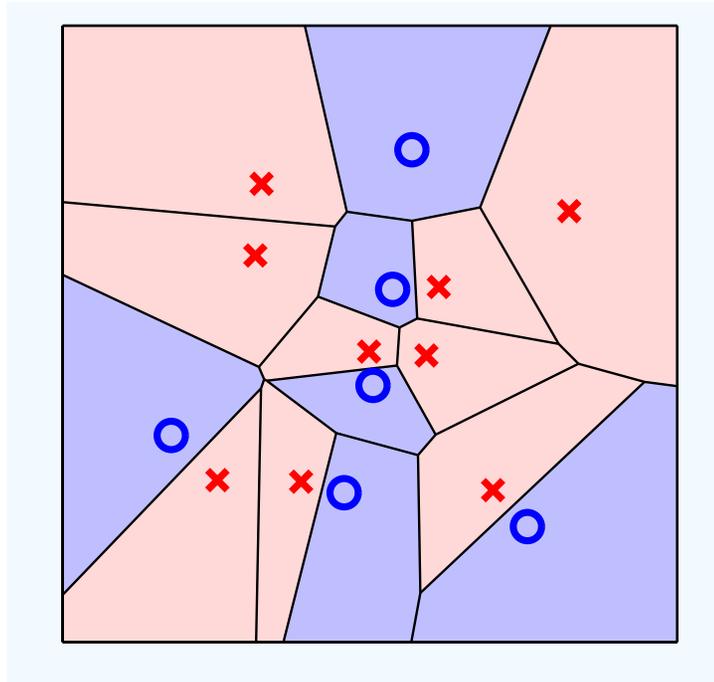
$$d(\mathbf{x}, \mathbf{x}_{[1]}) \leq d(\mathbf{x}, \mathbf{x}_{[2]}) \leq \dots \leq d(\mathbf{x}, \mathbf{x}_{[N]})$$

The prediction:

$$g(\mathbf{x}) = y_{[1]}(\mathbf{x})$$

Voronoi diagrams

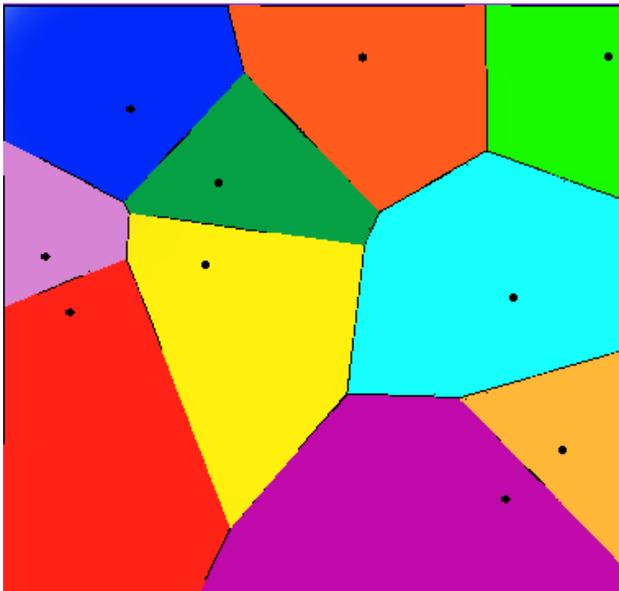
Voronoi diagram with respect to a collection of points x_1, \dots, x_N :



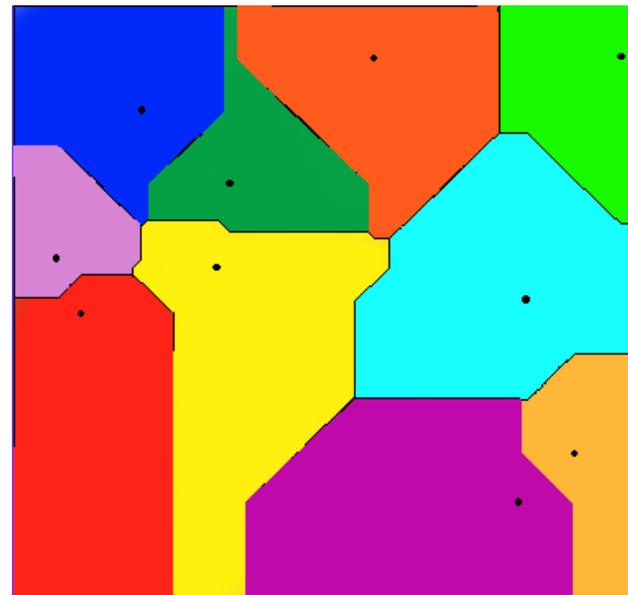
The Voronoi cell associated with point x_i is the set of points that are closer to x_i than every other point in the collection

Voronoi diagrams

The Voronoi diagram depends on the distance measure that is used:



Voronoi diagram computed from Euclidean distance (L2 norm)



Voronoi diagram computed from Manhattan distance (L1 norm)

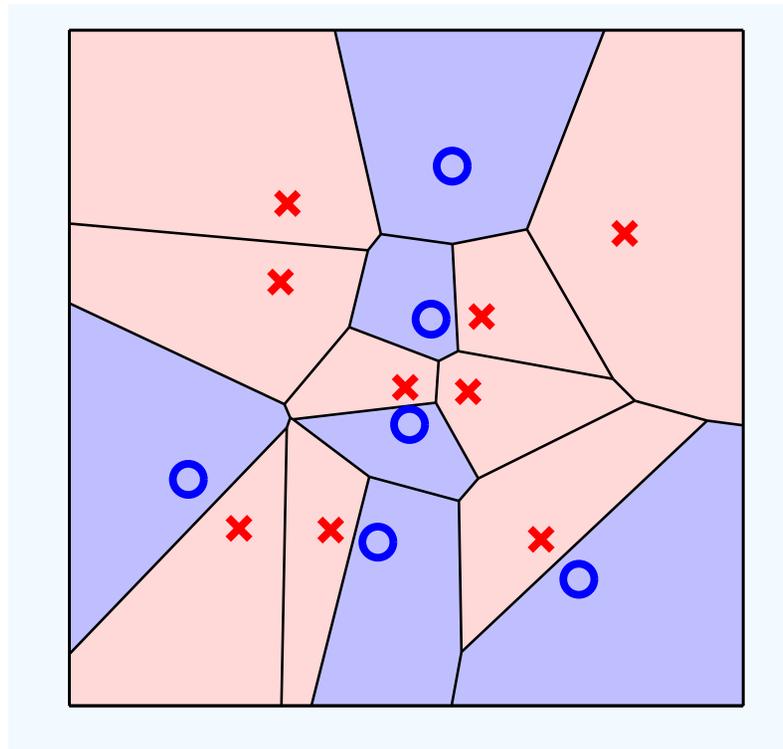
Image from http://en.wikipedia.org/wiki/Voronoi_diagram

Nearest neighbor classification

The *nearest neighbor classifier*:

Classify a given test example to the class of the nearest training example.

Decision boundary is the result of fusing adjacent Voronoi cells that are associated with the same class.



Nearest neighbor classification

The nearest neighbor classifier:

Classify a given test example to the class of the nearest training example.

What is the accuracy of the nearest neighbor classifier when it is tested on the training set? (i.e., what is E_{in})

Nearest neighbor classification

The nearest neighbor classifier:

Classify a given test example to the class of the nearest training example.

Property of the nearest neighbor classifier:

$E_{\text{out}} \leq 2E_{\text{out}}^*$ where E_{out}^* is the error of an optimal classifier

More precisely:

Theorem: For any $\delta > 0$ there is a sufficiently large N such that with probability $> 1 - \delta$ the resulting nearest neighbor classifier has $E_{\text{out}} \leq 2E_{\text{out}}^*$.

k-NN

Use the closest k neighbors to make a decision instead of a single nearest neighbor

Choose the majority label among the k nearest neighbors

Why do you expect this to work better?

k-NN

Use the closest k neighbors to make a decision instead of a single nearest neighbor

Choose the majority label among the k nearest neighbors

Can produce confidence scores. How?

k-NN

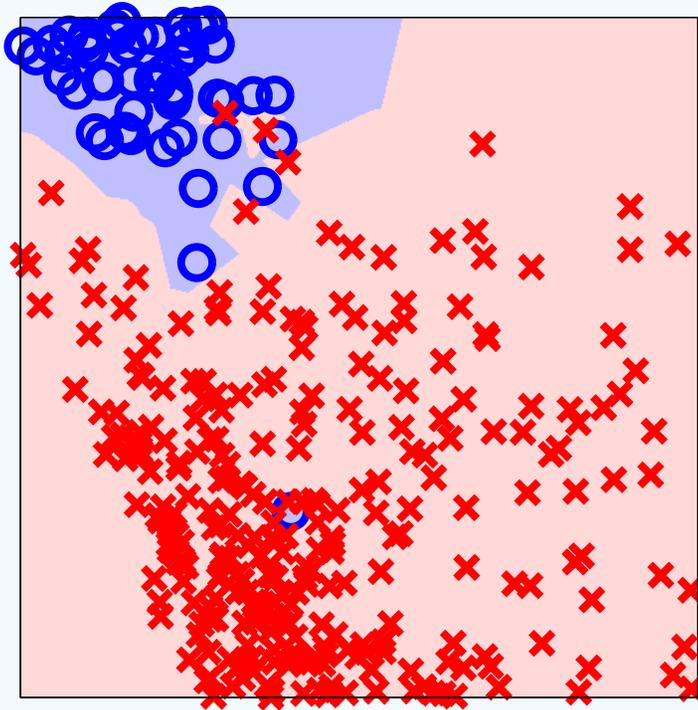
Use the closest k neighbors to make a decision instead of a single nearest neighbor

Choose the majority label among the k nearest neighbors

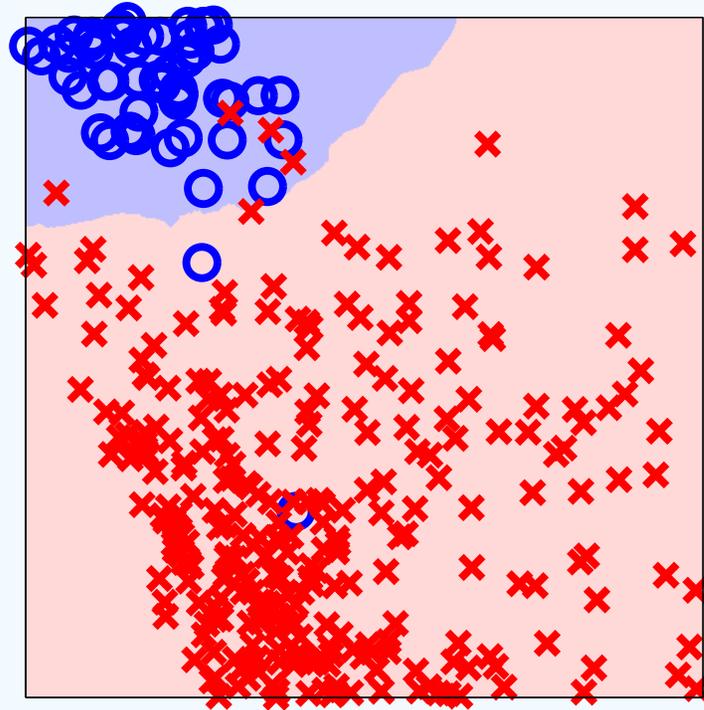
Other refinements: an example's vote is inversely proportional to its distance

NN vs k-NN

Decision boundary of NN vs k-NN on the digits data:



(a) 1-NN rule



(b) 21-NN rule

How to choose k?

The value of k can be chosen using cross-validation, like any classifier parameter:

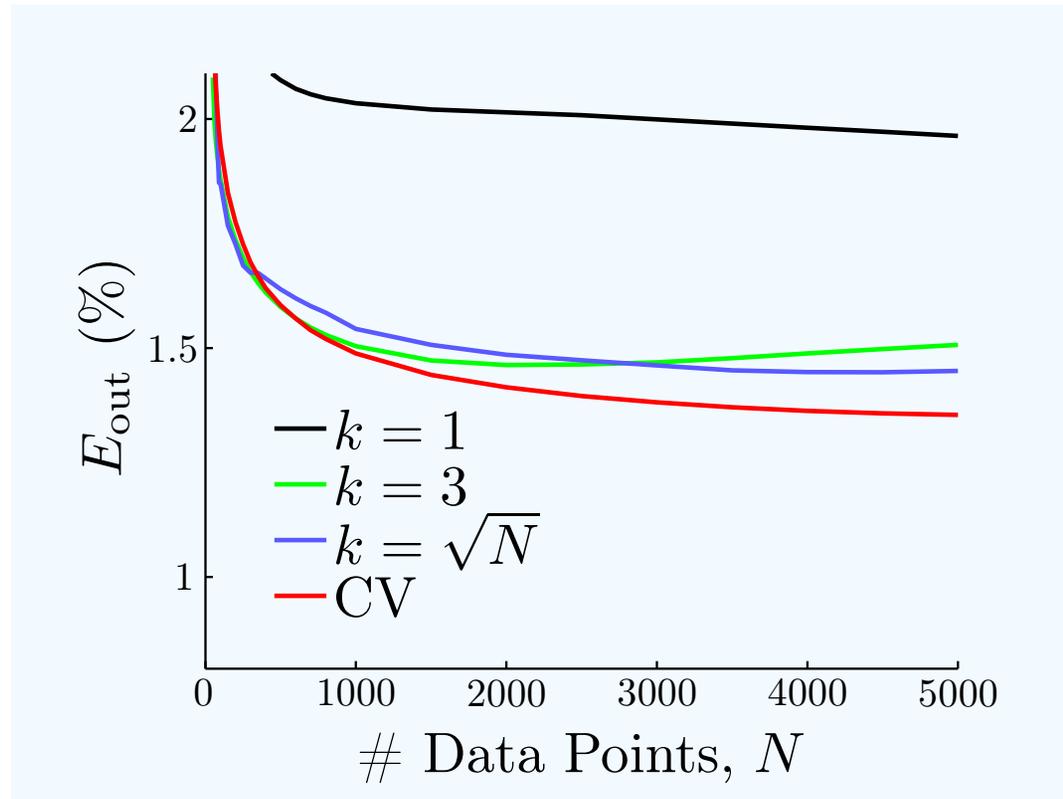


Figure 6.3 in chapter e-6

Interim conclusions

Properties of nearest neighbor classifiers:

- ❖ Simple and easy to implement
- ❖ No training required
- ❖ Expressive: can achieve zero training error
- ❖ Easy to explain the result

But...

- ❖ Running time can be an issue
- ❖ Not the best in terms of generalization

Nearest neighbor classification

The nearest neighbor classifier:

Classify a given test example to the class of the nearest training example.

Running time for testing an example when dataset has N examples?

Nearest neighbor classification

The *nearest neighbor classifier*:

Classify a given test example to the class of the nearest training example.

Running time for testing an example when dataset has N examples?

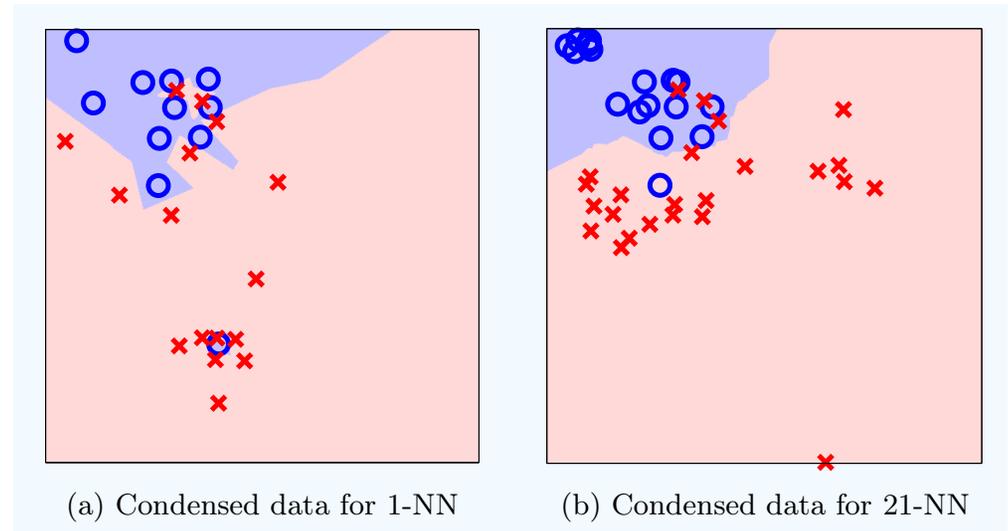
$O(N)$. Expensive when dealing with large datasets.

Nearest neighbor classification

Running time for testing an example when dataset has N examples is $O(N)$.

Solutions:

“Condense” the dataset



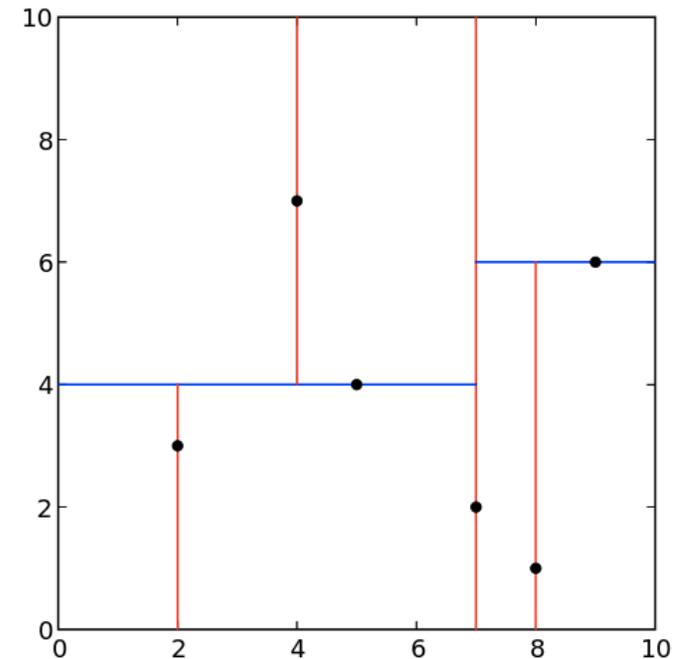
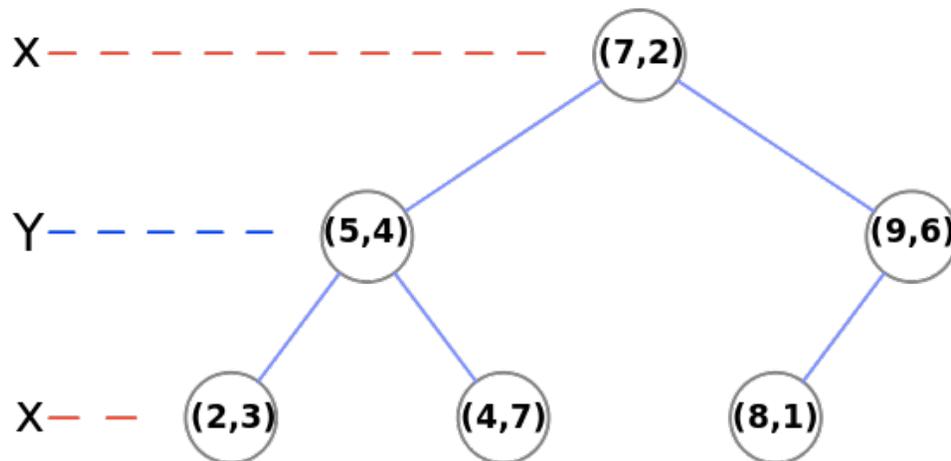
Efficient nearest neighbor search
(KD-trees, ball-trees, vantage-point trees)

KD-tree

Algorithm:

- ❖ Cycle through the coordinates
- ❖ Insert a node that corresponds to the median of the given coordinate, and put all other points in the left/right subtree on the basis of that coordinate

A KD-tree for the set of points
(2,3), (5,4), (9,6), (4,7), (8,1), (7,2).



KD-tree

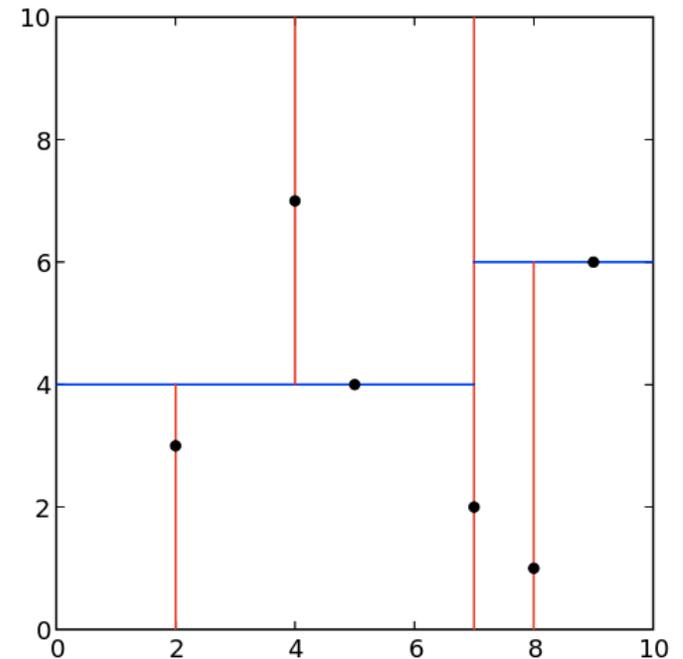
Algorithm:

- ❖ Cycle through the coordinates
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A KD-tree for the set of points
(2,3), (5,4), (9,6), (4,7), (8,1), (7,2).

Can be used for implementing nearest neighbor search in $O(\log N)$

Not effective for high dimensional data
(use ball-tree or vantage-point tree)



Nearest neighbor classification in high dimensions

Distance functions lose their usefulness in high dimensions.

Consider the Euclidean distance for example:

$$d_2(\mathbf{x}, \mathbf{x}') = \sqrt{\sum_{i=1}^d (x_i - x'_i)^2}$$

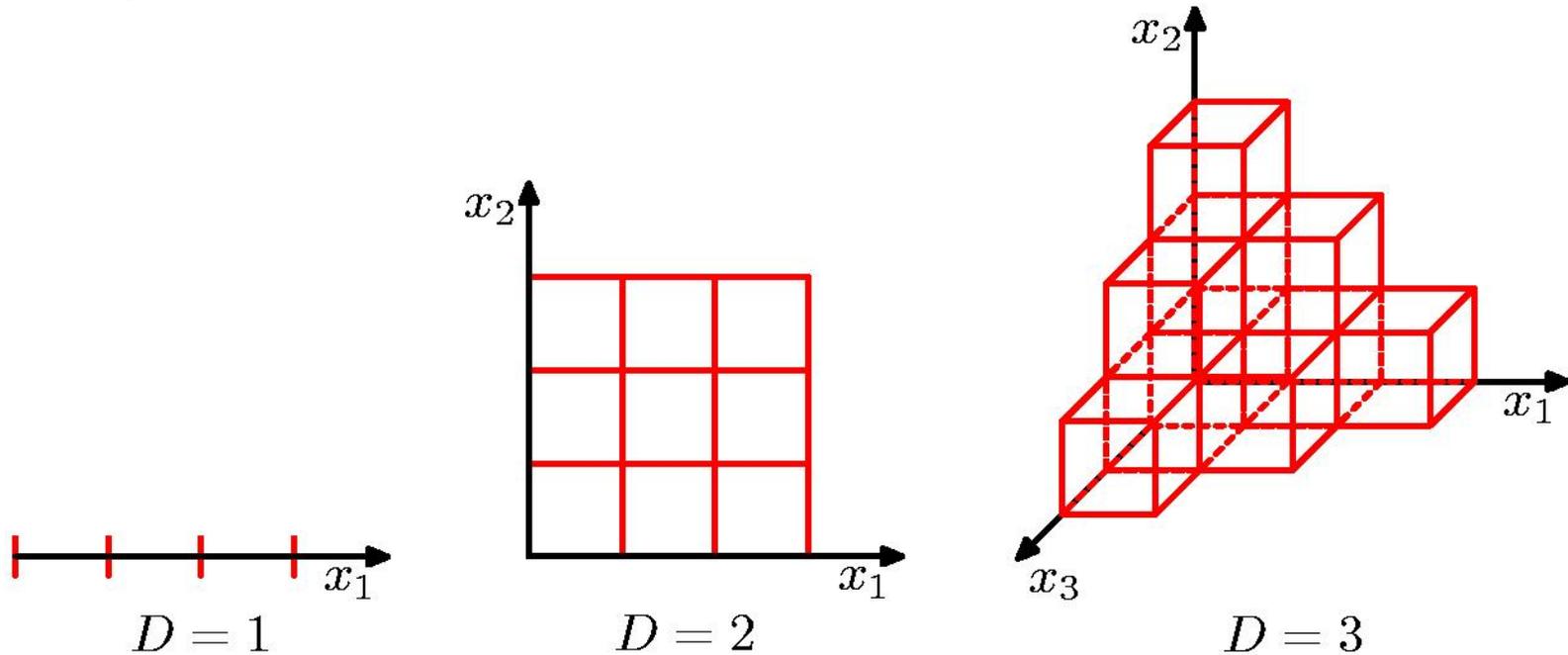
We expect that if d is large, many of the features won't be relevant, and so the signal contained in the informative dimensions can easily be corrupted by the noise.

This can lead to low accuracy of a nearest neighbor classifier.

Solution: feature selection, dimensionality reduction

The curse of dimensionality

An umbrella term for the issues that can arise in high dimensional data.



The curse of dimensionality

Some of our intuition from low dimensional spaces breaks in high dimensions.

Example: In high dimensions, most of the volume of the unit sphere is very close to its surface.

Let's compute the fraction of the volume that is between $r=1-\epsilon$ and $r=1$.

$$V_d(r) = k_d \cdot r^d$$

The required fraction is:

$$\frac{V_d(1) - V_d(1 - \epsilon)}{V_d(1)} = 1 - (1 - \epsilon)^d$$

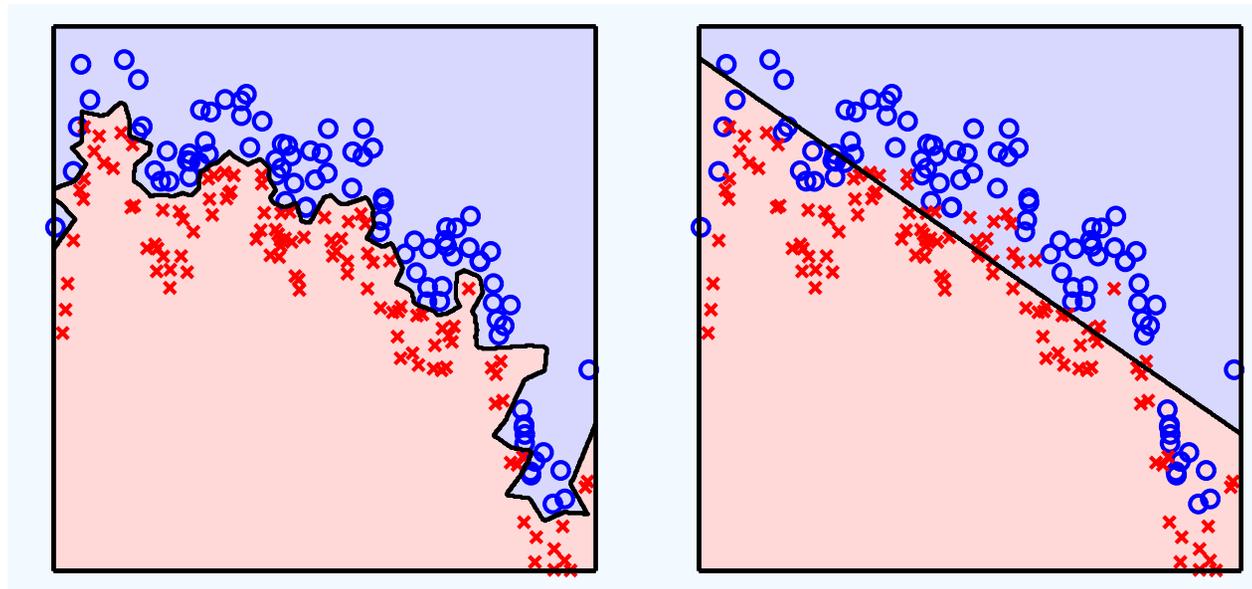
Related fact:

The ratio of the volume of the unit sphere and unit cube tends to 0 as d goes to infinity.

Non-parametric vs parametric methods

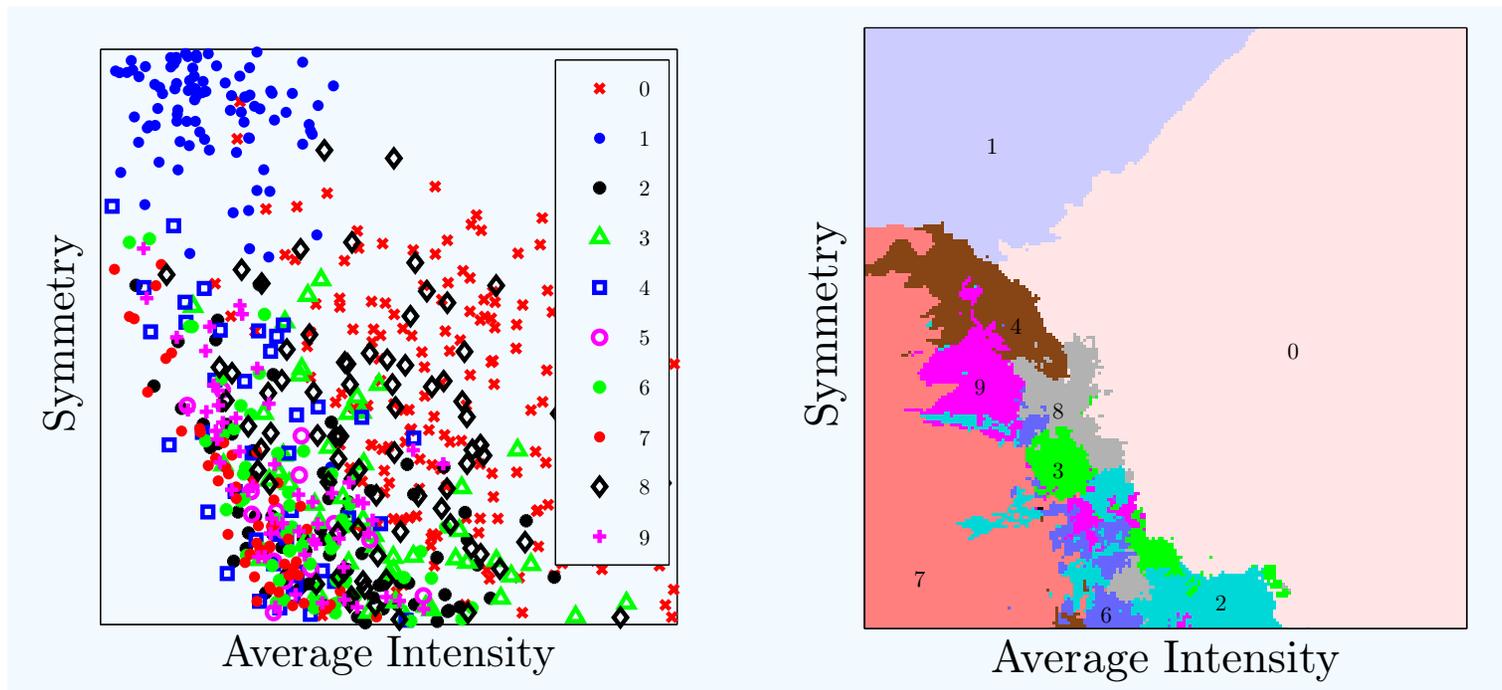
Non-parametric methods don't have any parameters that are learned from the data.

Parametric methods have a specific form that the learned model will have.



Multi-class problems

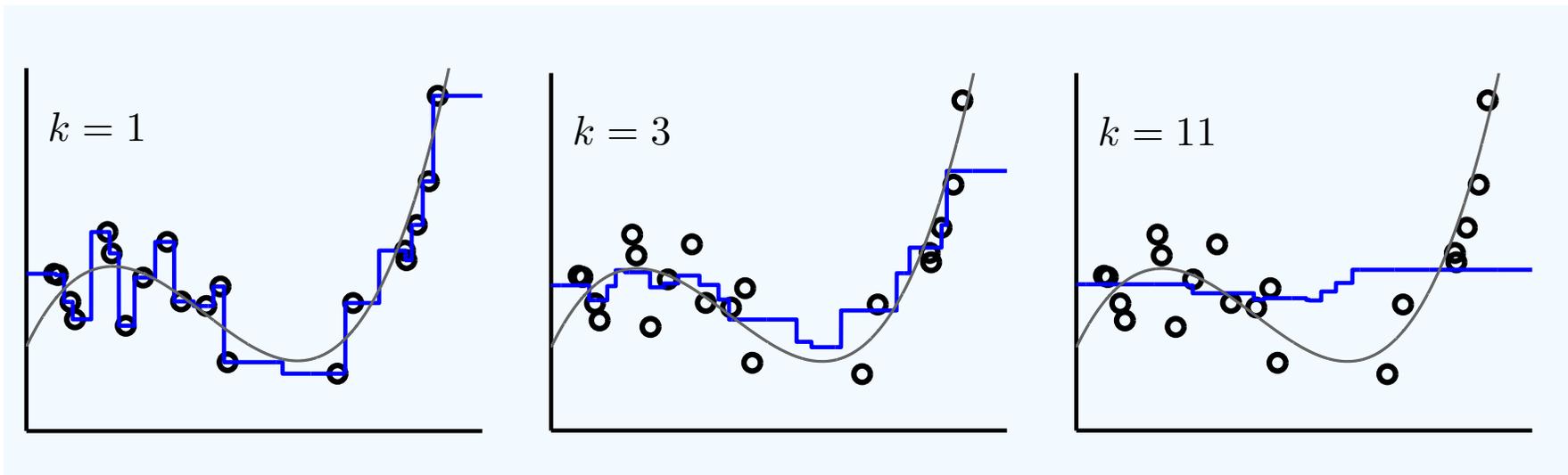
The nearest neighbor algorithm works much the same way for multi-class problems



In fact, nearest neighbor methods are easily adaptable to any ML problem.

Nearest neighbor regression

How do turn k-NN into a regression method?



Distances and kernels

The Euclidean distance can be expressed in terms of dot products:

$$Dis_2(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|_2 = \sqrt{(\mathbf{x} - \mathbf{y})^\top (\mathbf{x} - \mathbf{y})} = \sqrt{\mathbf{x}^\top \mathbf{x} - 2\mathbf{x}^\top \mathbf{y} - \mathbf{y}^\top \mathbf{y}}$$

Replacing dot products with kernels:

$$Dis_K(\mathbf{x}, \mathbf{y}) = \sqrt{K(\mathbf{x}, \mathbf{x}) - 2K(\mathbf{x}, \mathbf{y}) - K(\mathbf{y}, \mathbf{y})}$$

As an alternative, consider kernels as measures of similarity, and rather than looking for the closest points, look for the most similar points, and use kernels directly.

Distances and kernels

Replacing dot products with kernels:

$$Dis_K(\mathbf{x}, \mathbf{y}) = \sqrt{K(\mathbf{x}, \mathbf{x}) - 2K(\mathbf{x}, \mathbf{y}) + K(\mathbf{y}, \mathbf{y})}$$

If we consider a kernel that satisfies $K(\mathbf{x}, \mathbf{x}) = 1$, then nearest neighbor classification with kernels or distances is equivalent.

Summary

Nearest neighbor classification:

Pros:

- ❖ Simple and easy to implement
- ❖ No training involved
- ❖ One method that does it all

Cons:

- ❖ Accuracy suffers in high dimensions
- ❖ Testing speed is an issue for large datasets