Lecture 5: RNA folding

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Nearest Neighbor Model





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McCaskill's Algorithm for MFE Structure (1990) Notation

- straight horizontal line: nucleotides indexed from 1 to n.
- **solid arc:** a base pair.
- dashed arc: can be base pair or not.

- white region: open to more recursions.
- **cyan region:** finalized in the recursion, compute its energy contribution.
- **MFE** stands for *minimum free energy*.

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McCaskill's Algorithm for MFE Structure (1990)

General Case



$$S(i,j) = \min \begin{cases} G_{\text{unfolded}}(i,j) \\ G_{\text{unfolded}}(i,k_1-1) + S_b(k_1,k_2) + S(k_2+1,j) \\ \text{for } i \leq k_1 < k_2 \leq j \end{cases}$$

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McCaskill's Algorithm for MFE Structure (1990) Stack/Loop Case



$$S_b(i,j) = \min \begin{cases} G_{\text{hairpin}}(i,j) \\ G_{\text{stack/bulge/int}}(i,k_1,k_2,j) + S_b(k_1,k_2) \\ a_1 + a_2(k_1 - i - 1) + 2a_3 + S_b(k_1,k_2) + S_{bz}(k_2 + 1, j - 1) \\ \text{for } i < k_1 < k_2 < j \end{cases}$$

McCaskill's Algorithm for MFE Structure (1990)

Multiloop Case



$$S_{bz}(i,j) = \min \begin{cases} a_2(k_1 - i) + a_3 + S_b(k_1, k_2) + S_m(k_2 + 1, j) \\ \text{for } i \le k_1 < k_2 \le j \end{cases}$$

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McCaskill's Algorithm for MFE Structure (1990)

Multiloop Case (continued)



$$S_m(i,j) = \min \begin{cases} a_2(j-i+1) \\ a_2(k_1-i) + a_3 + S_b(k_1,k_2) + S_m(k_2+1,j) \\ \text{for } i \le k_1 < k_2 \le j \end{cases}$$

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Recall that multiloop energy is $a_1 + a_2U + a_3P$.

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Question: how about

1. computing base pairing probabilities,

2. sampling from the Boltzmann ensemble structures, clustering, centroids, etc.,

3. and computing equilibrium concentrations and melting temperature?

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Partition Function

$$Q(T) = \sum_{f \in F} e^{-G_f/RT},$$

F : All permissible foldings, i.e. the Boltzmann ensemble, T : Temperature, R : Gas constant,

$$p(f) \propto e^{-G_f/RT},$$

and Q is the normalizing factor. Also other thermodynamic quantities can be derived from Q.

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Partition Function Hardness \geq MFE Hardness

Partition function

$$\sum_{f\in F}e^{-G_f/RT}.$$

MFE secondary structure

$\operatorname{argmin}_{f \in F} G_f$.

Transform any partition function dynamic programming to an MFE algorithm by

$$e^{-G_f} \to G_f$$

 $\times \to +$
 $\Sigma \to \min$.

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$MFE \rightarrow Partition$ Function

Not always possible

In the partition function

$$\sum_{F\in F}e^{-G_f/RT},$$

every structure f is taken into account *exactly once*, whereas in the structure prediction

 $\operatorname{argmin}_{f\in F}G_f,$

every structure f is taken into account *at least once*.

Transform an *unambiguous* MFE dynamic programming to a partition function algorithm by

$$G_f \rightarrow e^{-G_f} + \rightarrow \times \min \rightarrow \Sigma.$$

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General Case



$$\begin{split} Q(i,j) &= e^{-G_{\text{unfolded}}(i,j)/RT} + \\ &\sum_{i \leq k_1 < k_2 \leq j} e^{-G_{\text{unfolded}}(i,k_1-1)/RT} Q_b(k_1,k_2) Q(k_2+1,j). \end{split}$$

Stack/Loop Case



$$\begin{split} Q_b(i,j) &= e^{-G_{\text{hairpin}}(i,j)/RT} + \\ &\sum_{i < k_1 < k_2 < j} e^{-G_{\text{stack/bulge/int}}(i,k_1,k_2,j)/RT} Q_b(k_1,k_2) + \\ &\sum_{i < k_1 < k_2 < j} e^{-[a_1 + a_2(k_1 - i - 1) + 2a_3]/RT} Q_b(k_1,k_2) Q_{bz}(k_2 + 1,j-1). \end{split}$$

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Multiloop Case



$$Q_{bz}(i,j) = \sum_{i \le k_1 < k_2 \le j} e^{-[a_2(k_1-i)+a_3]/RT} Q_b(k_1,k_2) Q_m(k_2+1,j).$$

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Multiloop Case (continued)



$$Q_m(i,j) = e^{-a_2(j-i+1)/RT} + \sum_{\substack{i \le k_1 < k_2 \le j}} e^{-[a_2(k_1-i)+a_3]/RT} Q_b(k_1,k_2) Q_m(k_2+1,j).$$

Ordering is important

- ▶ Pay attention to the order in which Q(i, j), Q_b(i, j), Q_{bz}(i, j), and Q_m(i, j) are computed.
- ► For instance, Q_m depends on Q_b because it has Q_b(i, j) as a term in its sum.
- Correct ordering: first Q_b then Q_m , Q_{bz} , and Q in parallel.