

**CS 370: OPERATING SYSTEMS**  
**[PROCESS SYNCHRONIZATION]**

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L11.1

Frequently asked questions from the previous class survey

- What is the difference between a semaphore and a mutex?
  - Mutex: locking mechanism, semaphore: signaling mechanism
- What is preemption?
- Remainder section?

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Topics covered in the lecture

- Classical process synchronization problems
  - Producer-Consumer problem
  - Readers Writers
  - Dining philosopher's problem
- Monitors
  - Solving dining philosopher's problem using monitors
- Midterm

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**CLASSIC PROBLEMS OF SYNCHRONIZATION**

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The bounded buffer problem

- Binary semaphore (**mutex**)
  - Provides mutual exclusion for accesses to buffer pool
  - Initialized to 1
- Counting semaphores
  - **empty**: Number of empty slots available to produce
    - Initialized to ***N***
  - **full**: Number of filled slots available to consume
    - Initialized to 0

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Some other things to bear in mind

- Producer and consumer must be **ready** before they **attempt to enter** critical section
- Producer readiness?
  - When a slot is available **to add** produced item
    - wait(**empty**): empty is initialized to ***N***
- Consumer readiness?
  - When a **producer has added** new item to the buffer
    - wait(**full**): full initialized to **0**

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### The Producer

```

do {
    produce item nextp
    wait(empty);
    wait(mutex);
    add nextp to buffer
    signal(mutex);
    signal(full);
    remainder section
} while (TRUE);
    
```

wait till slot available

Only producer OR consumer can be in critical section

Allow producer OR consumer to (re)enter critical section

signal consumer that a slot is available

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### The Consumer

```

do {
    wait(full);
    wait(mutex);
    remove item from buffer (nextc)
    signal(mutex);
    signal(empty);
    consume nextc
} while (TRUE);
    
```

wait till slot available for consumption

Only producer OR consumer can be in critical section

Allow producer OR consumer to (re)enter critical section

signal producer that a slot is available to add

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## THE READERS-WRITERS PROBLEM

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### The Readers-Writers problem

- A database is **shared** among several concurrent processes
- Two types of processes
  - ▣ Readers
  - ▣ Writers

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### Readers-Writers: Potential for adverse effects

- If **two readers** access shared data simultaneously?
  - ▣ No problems
- If a **writer and some other reader** (or writer) access shared data simultaneously?
  - ▣ Chaos

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### Writers must have exclusive access to shared database while writing

- **FIRST** readers-writers problem:
  - ▣ No reader should wait for other readers to finish; simply because a writer is waiting
    - ▣ Writers may starve
- **SECOND** readers-writers problem:
  - ▣ If a writer is ready it performs its write ASAP
    - ▣ Readers may starve

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### Solution to the FIRST readers-writers problem

- Variable `int readcount`
  - Tracks how many readers are reading object
- Semaphore `mutex {1}`
  - Ensure mutual exclusion when `readcount` is accessed
- Semaphore `wrt {1}`
  - ① Mutual exclusion for the writers
  - ② First (last) reader that enters (exits) critical section
    - Not used by readers, when other readers are in their critical section

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### The Writer: When a writer signals either a waiting writer or the readers resume

```
do {
    wait(wrt);
    writing is performed;
    signal(wrt);
} while (TRUE);
```

**When:**  
 writer in critical section and if n readers waiting  
 1 reader is queued on `wrt`  
 (n-1) readers queued on `mutex`

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### The Reader process

```
do {
    wait(mutex);
    readcount++;
    if (readcount == 1) {
        wait(wrt);
    }
    signal(mutex);
    reading is performed;
    wait(mutex);
    readcount--;
    if (readcount == 0) {
        signal(wrt);
    }
    signal(mutex);
} while (TRUE);
```

**mutex for mutual exclusion to readcount**

**When:**  
 writer in critical section and if n readers waiting  
 1 is queued on `wrt`  
 (n-1) queued on `mutex`

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## THE DINING PHILOSOPHERS PROBLEM

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### The situation

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### The Problem

- ① Philosopher tries to *pick up two closest {LR}* chopsticks
- ② Pick up only **1 chopstick at a time**
  - Cannot pick up a chopstick being used
- ③ Eat only when you have *both* chopsticks
- ④ When done; *put down both* the chopsticks

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### Why is the problem important?

- Represents allocation of **several resources**
  - ▣ AMONG **several processes**
- Can this be done so that it is:
  - ▣ Deadlock free
  - ▣ Starvation free

### Dining philosophers: Simple solution

- Each chopstick is a semaphore
  - ▣ Grab by executing `wait()`
  - ▣ Release by executing `signal()`
- Shared data
  - ▣ `semaphore chopstick[5];`
  - ▣ All elements are initialized to 1

### What if all philosophers get hungry and grab the same {L/R} chopstick?

```
do {  
    wait(chopstick[i]);  
    wait(chopstick[(i+1)%5]);  
  
    //eat  
  
    signal(chopstick[i]);  
    signal(chopstick[(i+1)%5]);  
  
    //think  
} while (TRUE);
```

Deadlock:  
If all processes  
access chopstick with  
same hand

We will look at solution with monitors

## MONITORS

### Overview of the semaphore solution

- Processes share a semaphore **mutex**
  - ▣ Initialized to 1
- Each process **MUST** execute
  - ▣ **wait** before entering critical section
  - ▣ **signal** after exiting critical section

### Incorrect use of semaphores can lead to timing errors

- Hard to detect
  - ▣ Reveal themselves only during specific execution sequences
- If correct sequence is not observed
  - ▣ 2 processes may be in critical section simultaneously
- Problems even if only one process is not well behaved

Incorrect use of semaphores: Interchange order of wait and signal [1/3]

```
do {
    signal(mutex);
    critical section
    wait(mutex);
    remainder section
} while (TRUE);
```

**Problem:** Several processes simultaneously active in critical section

NB: Not always reproducible

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Incorrect use of semaphores: Replace signal with wait [2/3]

```
do {
    wait(mutex);
    critical section
    wait(mutex);
    remainder section
} while (TRUE);
```

**Problem:** Deadlock!

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Incorrect use of semaphores: What if you omit signal AND/OR wait? [3/3]

```
do {
    wait(mutex);
    critical section
    signal(mutex);
    remainder section
} while (TRUE);
```

**Omission:** Mutual exclusion violated

**Omission:** Deadlock!

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When programmers use semaphores incorrectly problems arise

- We need a higher-level synchronization construct
  - ▣ **Monitor**
- Before we move ahead: Abstract Data Types
  - ▣ Encapsulates private data with
    - ▣ Public methods to operate on them

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A monitor is an abstract data type

- Mutual exclusion provided **within** the monitor
- Contains:
  - ▣ Declaration of variables
    - ▣ Defining the instance's state
  - ▣ Functions that operate on these variables

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Monitor construct ensures that only one process at a time is active within monitor

```
monitor monitor name {
    //shared variable declarations

    function F1(..) {.. ..}
    function F2(..) {.. ..}
    function Fn(..) {.. ..}

    initialization code(..) {.. ..}
}
```

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Programmer does not code synchronization constraint explicitly

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Basic monitor scheme not sufficiently powerful

- Provides an easy way to achieve mutual exclusion
- But ... we also need a way for processes to **block** when they cannot proceed

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This blocking capability is provided by the condition construct

- The **condition** construct
  - condition  $x, y$ ;
- Operations on a **condition** variable
  - wait: e.g.  $x.wait()$ 
    - Process invoking this is suspended UNTIL
  - signal: e.g.  $x.signal()$ 
    - Resumes exactly-one suspended process
    - If no process waiting; NO EFFECT on state of  $x$

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Semantics of wait and signal

- $x.signal()$  invoked by process  $P$
- $Q$  is the suspended process waiting on  $x$
- Signal and wait:  $P$  waits for  $Q$  to leave monitor
- Signal and continue:  $Q$  waits till  $P$  leaves monitor
- PASCAL: When thread  $P$  calls signal
  - $P$  leaves immediately
  - $Q$  immediately resumed

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Difference between the  $signal()$  in semaphores and monitors

- Monitors {condition variables}: Not persistent
  - If a signal is performed and no waiting threads?
    - Signal is simply ignored
  - During subsequent wait operations
    - Thread blocks
- Semaphores
  - Signal **increments** semaphore value *even if* there are no waiting threads
    - Future wait operations would immediately succeed!

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**DINING PHILOSOPHERS USING MONITORS**

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### Dining-Philosophers Using Monitors Deadlock-free

```
enum {THINKING,HUNGRY,EATING} state[5];
```

- state[i] = EATING only if
  - state[(i+4)%5] != EATING && state[(i+1)%5] != EATING
- condition self[5]
  - Delay self when **HUNGRY** but **unable** to get chopsticks

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### Sequence of actions

- Before eating, must invoke pickup ()
  - May result in suspension of philosopher process
  - After completion of operation, philosopher may eat

```
DiningPhilosophers.pickup(i);
...
eat
...
DiningPhilosophers.putdown(i);
```

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### The pickup() and putdown() operations

```
pickup(int i) {
    state[i] = HUNGRY;
    test(i);
    if (state[i] != EATING) {
        self[i].wait();
    }
}

putdown(int i) {
    state[i] = THINKING;
    test( (i+4)%5 );
    test( (i+1)%5 );
}
```

Suspend self if unable to acquire chopstick

Check to see if person on left or right can use the chopstick

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### test() to see if philosopher can eat

```
test(int i) {
    if (state[(i+4)%5] != EATING &&
        state[i] == HUNGRY &&
        state[(i+1)%5] != EATING) {
        state[i] = EATING;
        self[i].signal();
    }
}
```

Eat only if HUNGRY and Person on Left AND Right are **not** eating

Signal a process that was suspended while trying to eat

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### Possibility of starvation

- Philosopher **i** can **starve** if eating periods of philosophers on left and right overlap
- Possible solution
  - Introduce new state: STARVING
  - Chopsticks can be picked up if **no** neighbor is starving
    - Effectively wait for neighbor's neighbor to stop eating
    - REDUCES concurrency!

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## MIDTERM

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### Midterm will be for 80 points

- Processes and Inter-Process Communications: 30 points
- Threads: 20 points
- Process Synchronization: 30 points

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### The contents of this slide set are based on the following references

- *Avi Silberschatz, Peter Galvin, Greg Gagne. Operating Systems Concepts, 9<sup>th</sup> edition. John Wiley & Sons, Inc. ISBN-13: 978-1118063330. [Chapter 5]*
- *Andrew S Tanenbaum and Herbert Bos. Modern Operating Systems. 4<sup>th</sup> Edition, 2014. Prentice Hall. ISBN: 013359162X/ 978-0133591620. [Chapter 2]*

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